



# Radon Cumulative Distribution Transform

This notebook implements the Radon Cumulative Distribution Transform (Radon-CDT) and its inverse and showcases an example application of this transformation.

## CDT Definition: ¶

Consider two nonzero probability density functions  $I_0$  and  $I_1$  defined on  $X, Y \subset \mathbb{R}$ . Considering  $I_0$  to be a pre-determined 'reference' density, one can use the following relation,

$$\int_{\inf(Y)}^{f(x)} I_1(\tau) d\tau = \int_{\inf(X)}^x I_0(\tau) d\tau \quad (1)$$

to uniquely associate  $f_1 : X \rightarrow Y$  to the given density  $I_1$ . We use this relationship to define the Cumulative Distribution Transform (CDT) of  $I_1$  (denoted as  $\hat{I}_1 : X \rightarrow \mathbb{R}$ ), with respect to the reference  $I_0$ :

$$\hat{I}_1(x) = (f_1(x) - x) \sqrt{I_0(x)}. \quad (2)$$

Now let  $J_0 : X \rightarrow [0, 1]$  and  $J_1 : Y \rightarrow [0, 1]$  be the corresponding cumulative distribution functions for  $I_0$  and  $I_1$ , that is:  $J_0(x) = \int_{\inf(X)}^x I_0(\tau) d\tau$ ,  $J_1(y) = \int_{\inf(Y)}^y I_1(\tau) d\tau$ . Equation (1) can then be rewritten as,

$$J_0(x) = J_1(f_1(x)) \Rightarrow f_1(x) = J_1^{-1}(J_0(x)). \quad (3)$$

For continuous cumulative distribution functions  $J_0$  and  $J_1$ ,  $f_1$  is a continuous and monotonic function. If  $f_1$  is differentiable, Equation (3) can be rewritten as

$$I_0(x) = f'_1(x) I_1(f_1(x)). \quad (4)$$

## Inverse-CDT Definition:

The Inverse-CDT of  $\hat{I}_1$  is defined as:

$$I_1(y) = \frac{d}{dy} J_0(f_1^{-1}(y)) = (f_1^{-1})' I_0(f_1^{-1}(y))$$

where  $f_1^{-1} : Y \rightarrow X$  refers to the inverse of  $f_1$  (i.e.  $f_1^{-1}(f_1(x)) = x$ ),  $f(x) = \hat{I}_1(x)/\sqrt{I_0(x)} + x$ , and where  $I_1 : Y \rightarrow \mathbb{R}$  as before. Naturally, the equation above holds for points where  $J_0$  and  $f$  are differentiable. By the construction above,  $f$  will be differentiable except for points where  $I_0$  and  $I_1$  are discontinuous.

## Radon-CDT Definition:

Radon-CDT extends the concept of CDT to higher dimensional probability distributions, by projecting the high-dimensional pdf into a set of one-dimensional pdfs via Radon transform and applying CDT to these projections. To define Radon-CDT we first define the Radon transform. The  $d$ -dimensional Radon transform  $\mathcal{R}$  maps a function  $I \in L^1(\mathbb{R}^d)$  where  $L^1(\mathbb{R}^d) := \{I : \mathbb{R}^d \rightarrow \mathbb{R} \mid \int_{\mathbb{R}^d} |I(x)| dx \leq \infty\}$  into the set of its integrals over the hyperplanes of  $\mathbb{R}^n$  and is defined as,

$$\mathcal{R}I(t, \theta) := \int_{\mathbb{R}} I(t\theta + \gamma\theta^\perp) d\gamma$$

here  $\theta^\perp$  is the subspace or unit vector orthogonal to  $\theta$ . Note that  $\mathcal{R} : L^1(\mathbb{R}^d) \rightarrow L^1(\mathbb{R} \times \mathbb{S}^{d-1})$ , where  $\mathbb{S}^{d-1}$  is the unit sphere in  $\mathbb{R}^d$ . We note that the Radon transform is an invertible, linear transform and we denote its inverse as  $\mathcal{R}^{-1}$ . For brevity we do not define the inverse Radon transform here, but the details can be found in

(Natterer, Frank. The mathematics of computerized tomography. Society for Industrial and Applied Mathematics, 2001.).

Given a template distribution  $I_0 \in L^1(\mathbb{R}^d)$ , the Radon-CDT of the probability distribution  $I \in L^1(\mathbb{R}^d)$  is then defined as:

$$\tilde{I}(t, \theta) = (f(t, \theta) - t) \sqrt{\mathcal{R}I_0(t, \theta)}$$

where  $f(t, \theta)$  satisfies:

$$\int_{-\infty}^{f(t, \theta)} \mathcal{R}I_1(\tau, \theta) d\tau = \int_{-\infty}^t \mathcal{R}I_0(\tau, \theta) d\tau, \forall \theta \in \mathbb{S}^{d-1}$$

## Inverse Radon-CDT Definition:

The inverse Radon-CDT is defined as:

$$I = \mathcal{R}^{-1}(\det(Dg)\mathcal{R}I_0(g))$$

where  $\det(Dg)$  is the determinant of Jacobian of  $g$  and  $g : \mathbb{R} \times \mathbb{S}^{d-1} \rightarrow \mathbb{R} \times \mathbb{S}^{d-1}$  is defined as,  $g(t, \theta) = (f^{-1}(t, \theta), \theta)$ .

## Now we implement Radon-CDT in python

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
from sklearn.discriminant_analysis import LinearDiscriminantAnalysis as LDA
from skimage.transform import radon, iradon
from scipy import interp
from skimage.io import imread
from scipy.ndimage import filters
from sklearn.svm import LinearSVC
from matplotlib import colors
from skimage.color import rgb2gray
%matplotlib inline

/Users/skolouri/anaconda/lib/python2.7/site-packages/matplotlib/font_manager.py:273: UserWarning: Matplotlib is building the font cache using fc-list. This may take a moment.
  warnings.warn('Matplotlib is building the font cache using fc-list. This may take a moment.')
```

## Define CDT and its inverse

```
In [2]: def CDT(I0,I1):
    assert I0.shape==I1.shape
    assert not((1.0*I0<0).sum() and (1.0*I1<0).sum())
    I0=I0/I0.sum()
    I1=I1/I1.sum()
    cI0=np.cumsum(I0)
    cI1=np.cumsum(I1)
    x=np.asarray(range(len(I0)))
    xtilde=np.linspace(0,1,len(I0))
    XI0 = interp(xtilde,cI0, x)
    XI1 = interp(xtilde,cI1, x)
    u = interp(x,XI0,XI0-XI1)
    f = x - u
    return u,f
def iCDT(u,I0):
    x=np.asarray(range(len(I0)))
    f=x-u
    fprime=np.gradient(f)
    I1 = interp(x,f, I0/fprime)
    return I1
def RadonCDT(I1,theta=np.asarray(range(180))):
    R1 = radon(I1, theta=theta, circle=False)
    R0 = np.ones_like(R1)
    rcdt=[ ]
    for i in range(len(theta)):
        u,f=CDT(R0[:,i],R1[:,i])
        rcdt.append(u)
    rcdt=np.asarray(rcdt).T
    return rcdt

def iRadonCDT(rcdt,theta=np.asarray(range(180))):
    J0=np.ones([rcdt.shape[0]])
    J0=J0/J0.sum()
    R=[ ]
    for i in range(rcdt.shape[1]):
        R.append(iCDT(rcdt[:,i],J0))
    R=np.asarray(R).T
    I=iradon(R,theta=theta)
    return I
```

To demonstrate the nonlinear nature of our transformation we simply take the average of two 2D images in the image space and in the Radon-CDT space

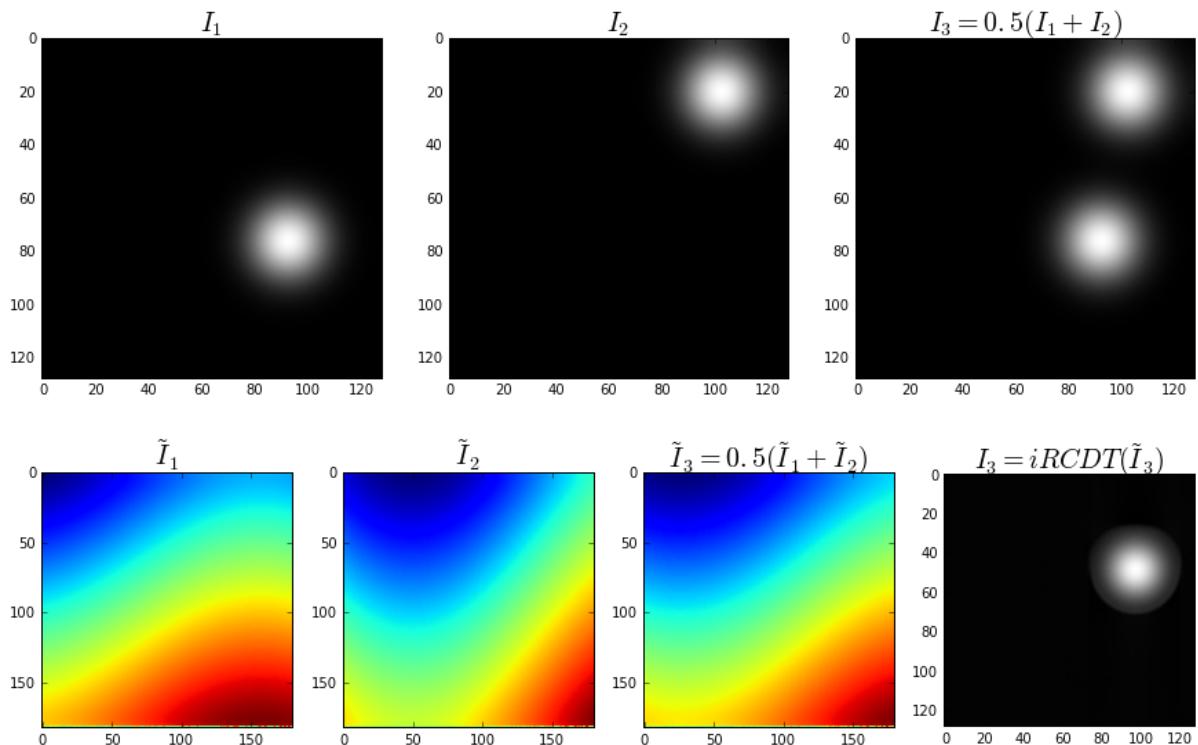
```
In [17]: I1=np.zeros((128,128))
x,y=np.random.uniform(20,108,(2,)).astype('int')
I1[x,y]=1
I1=filters.gaussian_filter(I1,sigma=10)
I2=np.zeros((128,128))
x,y=np.random.uniform(20,108,(2,)).astype('int')
I2[x,y]=1
I2=filters.gaussian_filter(I2,sigma=10)
```

```
In [18]: RI1=RadonCDT(I1)
          RI2=RadonCDT(I2)
```

```
In [19]: I3=0.5*(I1+I2)
          RI3=0.5*(RI1+RI2)
          iRI3=iRadonCDT(RI3)
```

```
In [20]: fig,[ax1,ax2,ax3]=plt.subplots(1,3,figsize=(15,15))
          ax1.imshow(I1,cmap='gray')
          ax1.set_title('$I_1$',fontsize=20)
          ax2.imshow(I2,cmap='gray')
          ax2.set_title('$I_2$',fontsize=20)
          ax3.imshow(I3,cmap='gray')
          ax3.set_title('$I_3=0.5(I_1+I_2)$',fontsize=20)
          plt.show()
          fig,[ax1,ax2,ax3,ax4]=plt.subplots(1,4,figsize=(15,15))
          ax1.imshow(RI1)
          ax1.set_title('$\sim I_1$',fontsize=20)
          ax2.imshow(RI2)
          ax2.set_title('$\sim I_2$',fontsize=20)
          ax3.imshow(RI3)
          ax3.set_title('$\sim I_3=0.5(\sim I_1+\sim I_2)$',fontsize=20)
          ax4.imshow(iRI3,cmap='gray')
          ax4.set_title('$I_3=iRCDT(\sim I_3)$',fontsize=20)

          plt.show()
```



```
In [7]: N=1000
C1=np.zeros((N,128,128))
C2=np.zeros((N,128,128))
C3=np.zeros((N,128,128))
K,L=RadonCDT(1+C1[0,:,:]).shape

RC1=np.zeros((N,K,L))
RC2=np.zeros((N,K,L))
RC3=np.zeros((N,K,L))

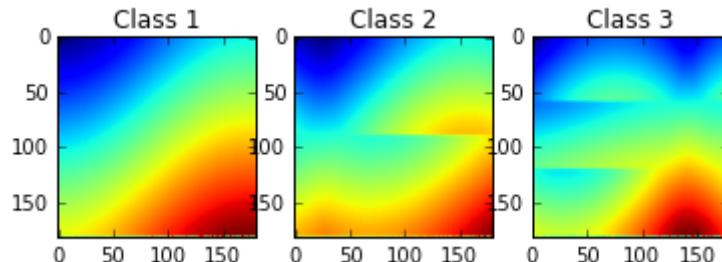
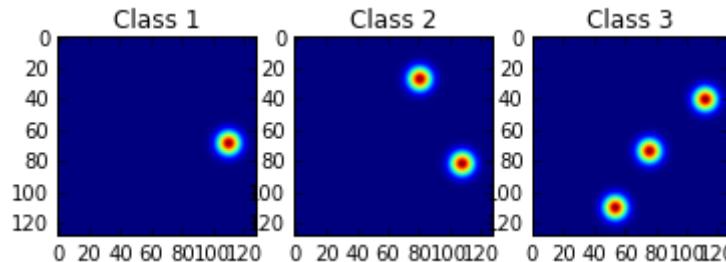
for i in range(N):
    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C1[i,x,y]=1
    C1[i,:,:]=filters.gaussian_filter(C1[i,:,:],sigma=5)

    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C2[i,x,y]=0.5
    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C2[i,x,y]=0.5
    C2[i,:,:]=filters.gaussian_filter(C2[i,:,:],sigma=5)

    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C3[i,x,y]=0.333
    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C3[i,x,y]=0.333
    x,y=np.random.uniform(10,118,(2,)).astype('int')
    C3[i,x,y]=0.333
    C3[i,:,:]=filters.gaussian_filter(C3[i,:,:],sigma=5)

    RC1[i,:,:]=RadonCDT(C1[i,:,:])
    RC2[i,:,:]=RadonCDT(C2[i,:,:])
    RC3[i,:,:]=RadonCDT(C3[i,:,:])
```

```
In [8]: fig,[ax1,ax2,ax3]=plt.subplots(1,3)
ax1.imshow(C1[0,:,:])
ax1.set_title('Class 1')
ax2.imshow(C2[0,:,:])
ax2.set_title('Class 2')
ax3.imshow(C3[0,:,:])
ax3.set_title('Class 3')
plt.show()
fig,[ax1,ax2,ax3]=plt.subplots(1,3)
ax1.imshow(RC1[0,:,:])
ax1.set_title('Class 1')
ax2.imshow(RC2[0,:,:])
ax2.set_title('Class 2')
ax3.imshow(RC3[0,:,:])
ax3.set_title('Class 3')
plt.show()
```



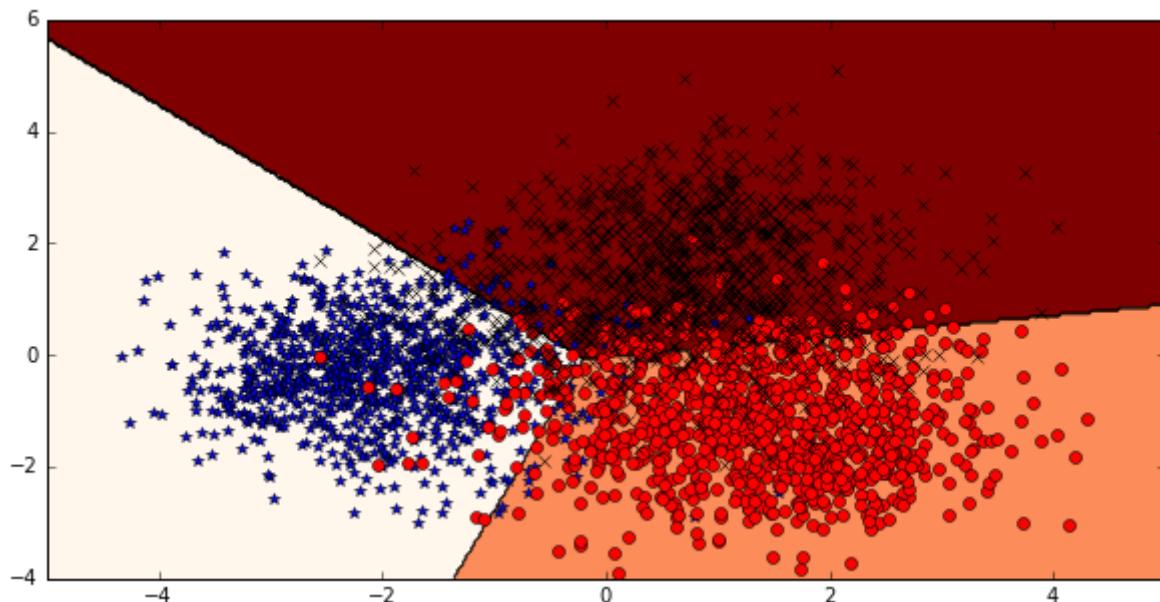
```
In [9]: X=np.concatenate((np.concatenate((np.reshape(C1,
[N,128*128]),np.reshape(C2,[N,128*128])),0),np.reshape(C3,
[N,128*128])),0)
Xhat=np.concatenate((np.concatenate((np.reshape(RC1,
[N,K*L]),np.reshape(RC2,[N,K*L])),0),np.reshape(RC3,[N,K*L])),0)
label=np.concatenate((np.concatenate((np.zeros(N),np.ones(N)),0),2*np.ones(N)),0)
```

```
In [10]: lda=LDA(n_components=2)
```

```
In [11]: n=N
# Apply LDA and show classification boundaries in Signal Space
Xlda=lda.fit_transform(X,label)
svm=LinearSVC()
svm.fit(Xlda,label)

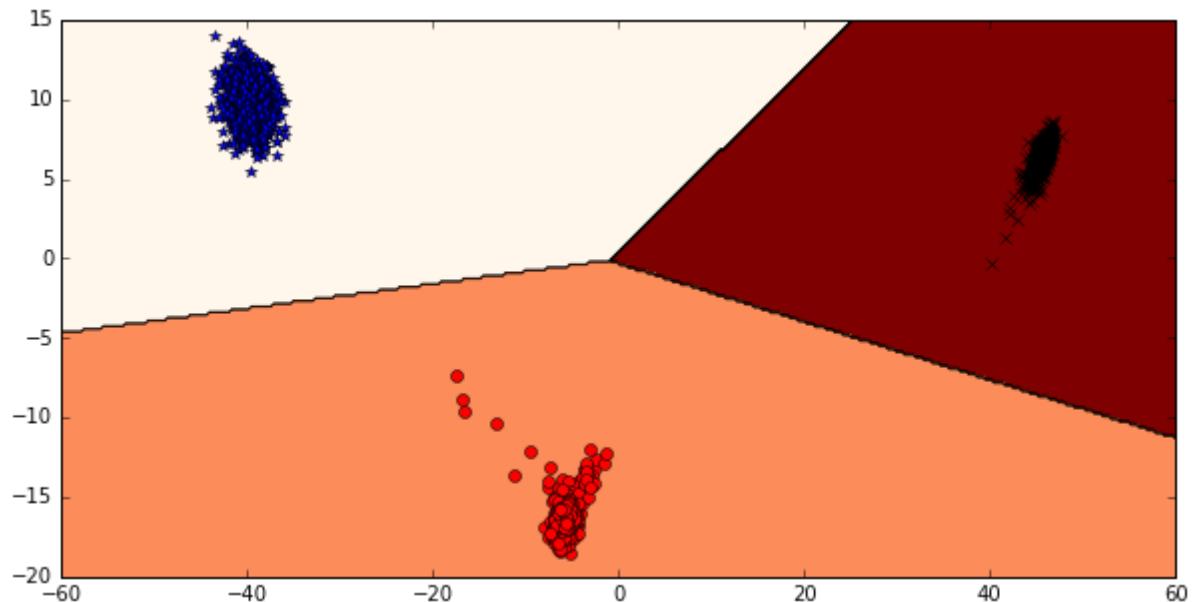
plt.figure(figsize=(10,5))
plt.plot(Xlda[:n,0],Xlda[:n,1],'b*')
plt.plot(Xlda[n:2*n,0],Xlda[n:2*n,1],'ro')
plt.plot(Xlda[2*n:,0],Xlda[2*n:,1],'kx')
x_min, x_max = plt.xlim()
y_min, y_max = plt.ylim()
nx, ny = 400, 200
xx, yy = np.meshgrid(np.linspace(x_min, x_max, nx),
                      np.linspace(y_min, y_max, ny))
z = svm.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z[:,].reshape(xx.shape)
plt.pcolormesh(xx, yy, Z,cmap='OrRd')
plt.contour(xx, yy, z, linewidths=.5, colors='k')
plt.show()
```

/Users/skolouri/anaconda/lib/python2.7/site-packages/sklearn/discrimina  
nt\_analysis.py:387: UserWarning: Variables are collinear.  
warnings.warn("Variables are collinear.")



```
In [12]: # Apply LDA and show classification boundaries in the transform Space
Xhatlda=lda.fit_transform(Xhat,label)
svm=LinearSVC()
svm.fit(Xhatlda,label)

plt.figure(figsize=(10,5))
plt.plot(Xhatlda[:n,0],Xhatlda[:n,1],'b*')
plt.plot(Xhatlda[n:2*n,0],Xhatlda[n:2*n,1],'ro')
plt.plot(Xhatlda[2*n:,0],Xhatlda[2*n:,1],'kx')
x_min, x_max = plt.xlim()
y_min, y_max = plt.ylim()
nx, ny = 400, 200
xx, yy = np.meshgrid(np.linspace(x_min, x_max, nx),
                      np.linspace(y_min, y_max, ny))
Z = svm.predict(np.c_[xx.ravel(), yy.ravel()])
Z = Z[:].reshape(xx.shape)
plt.pcolormesh(xx, yy, Z,cmap='OrRd')
plt.contour(xx, yy, Z, linewidths=.5, colors='k')
plt.show()
```



```
In [ ]:
```