

Transport transforms for signal analysis and machine learning

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imagedatascience.com/transport
github.com/rohdelab/PyTransKit

“... we get by with a little help from our friends ...”

(current)

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Xuwang Yin
M. Shifat E Rabbi
Hasnat Rubaiyat
Shying Li

(past)

Mohammad Hassan
Cailey Fitzgerald
Liam Cattell
Wei Wang
Saurav Basu
Soheil Kolouri
Serim Park
Shinjini Kundu
Chi Liu
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Shreyas Hirway
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Can we build smart systems cheaply with machine learning techniques?



Example applications:

- Face recognition
- Medical diagnosis
 - (pathology, radiology)
- Optical character recognition
- EKG diagnosis
- Self driving cars
- Speech recognition
- ...

What mathematical model shall we use?

How do we partition these data classes?

Outline

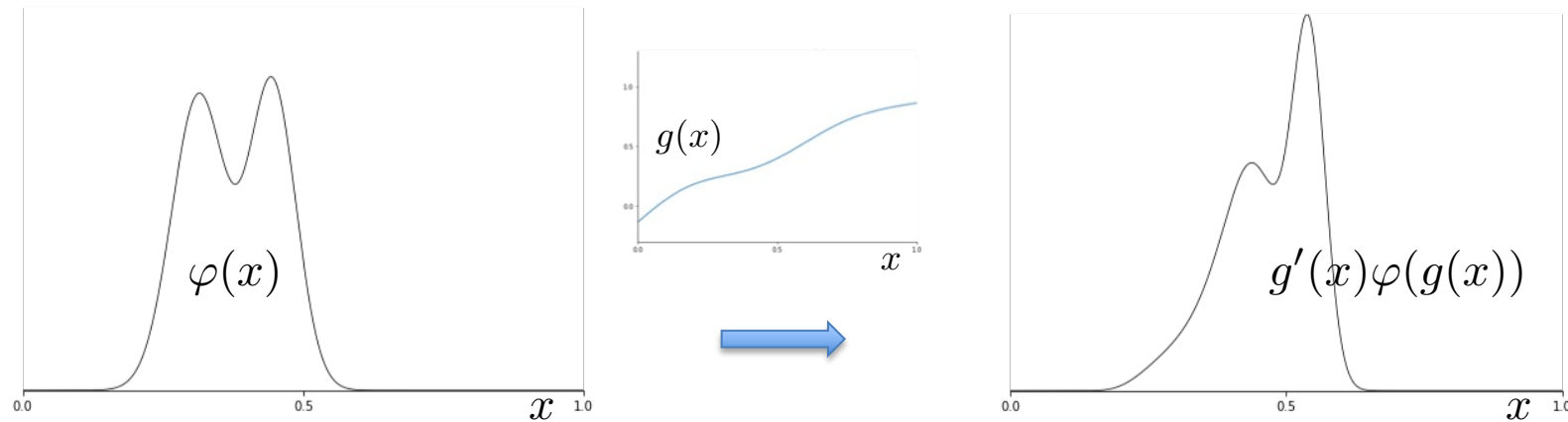
- Modeling signal and image data
 - What are we talking about?
 - Transport model & problem statement
- Transport embeddings (representations, transforms)
 - 1D transform (CDT), ND (R-CDT, LOT),
 - Properties
- Applications
 - Signal/image classification
 - Transport-based morphometry

Matthew Thorpe
Caroline Mossmueller
Q. Merigot
A. Cloninger
D. Slepcev
D. Nguyen
B. Schmitzer

...

Modeling signal and image data

Model for signal/image deformations (transportations)



Translation:

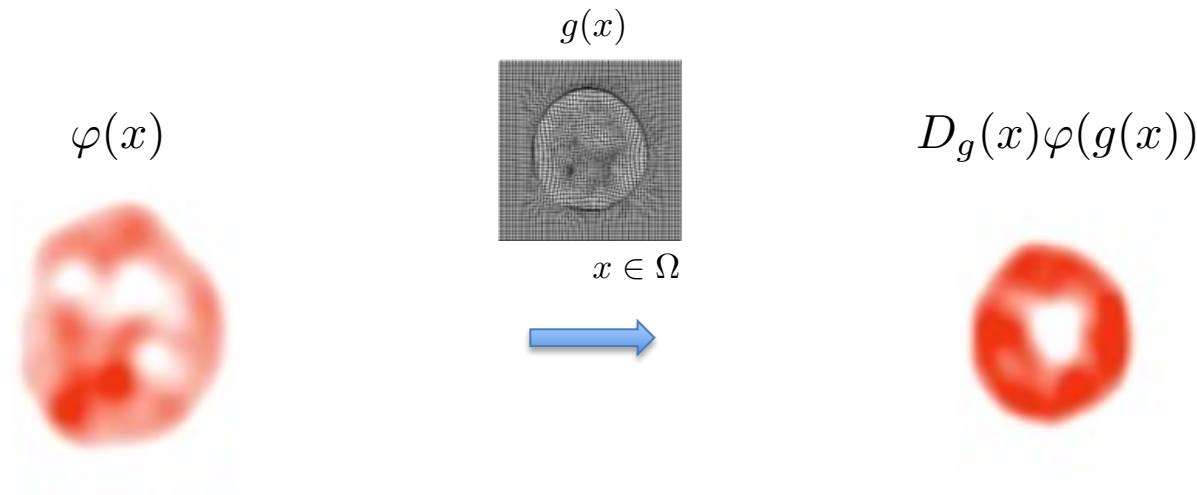
$$g(x) = x - \tau$$

Scaling:

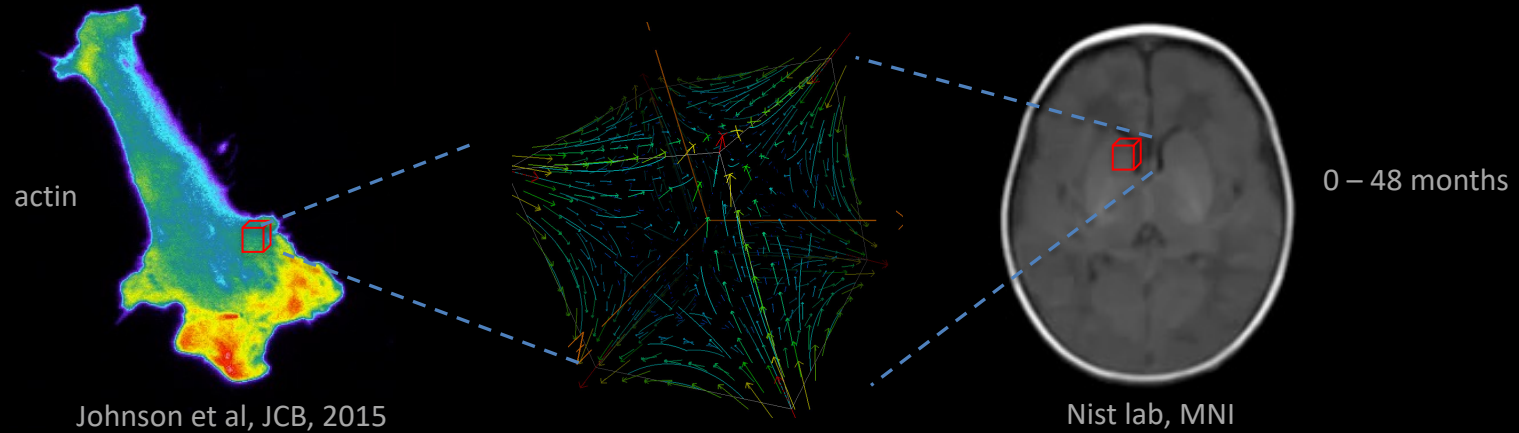
$$g(x) = ax$$

Nonrigid deformations:

$$g(x) = \sum_k c_k \phi_k(x)$$



What processes change signal/pixel intensity over time?



continuity equation

$$\underbrace{\frac{dI(x, y, z, t)}{dt}}_{\text{change in intensity at particular location}} = - \underbrace{\nabla \cdot (I(x, y, z, t) \mathbf{v}(x, y, z, t))}_{\text{net flux tissue velocity}} + \underbrace{\cancel{S(x, y, z, t)}}_{\text{source/sink term}}$$

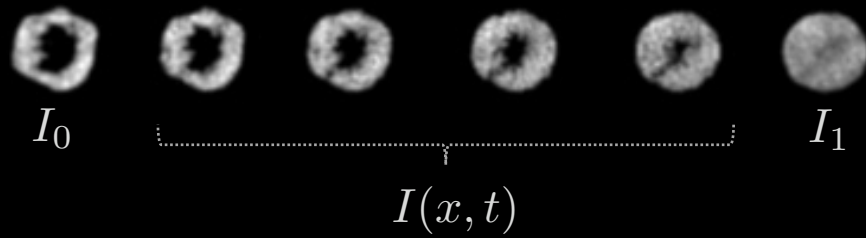
intensities not absolute

change in intensity at
particular location

net flux
tissue velocity

source/sink term

Transport with least action (optimal transport)



$$\left. \begin{array}{l} I(x, 0) = I_0(x) \\ I(x, 1) = I_1(x) \end{array} \right\} \begin{array}{l} \text{sample images} \\ \text{in a dataset} \end{array}$$

$$\frac{dI(x, t)}{dt} = -\nabla \cdot (I(x, y)v(x, t)) \quad \text{implies}$$

$$I(x, t) = D_f(x)I_0(f(x, t))$$

$$f(x, t) = \int_0^t v(x, t)dt$$

Theorem: [Benamou, Brenier, Numer. Math, 2000]

$$W^2(I_0, I_1) = \inf_v \int_0^1 \int_{\Omega} I(x, t)|v(x, t)|^2 dx dt$$

$$f(x, t) = (1 - t)x + t\nabla\phi \quad \text{gradient of convex function}$$

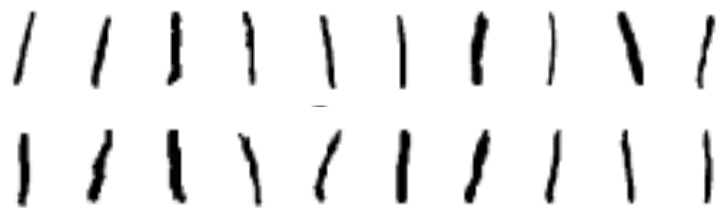
Model for signal/image classes

An image class is modeled as

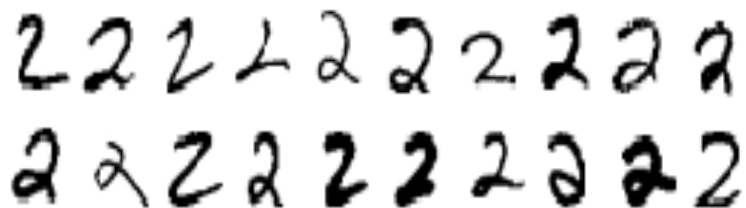
a set of transport maps $g_j \in \mathcal{G}$

applied to a template $\varphi^{(k)}$

$\mathbb{S}^1$: class for digit 1



$\mathbb{S}^2$: class for digit 2



$$\mathbb{S}^{(1)} = \left\{ s_j^{(1)} \mid s_j^{(1)} = |\det J g_j| \varphi^{(1)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$$

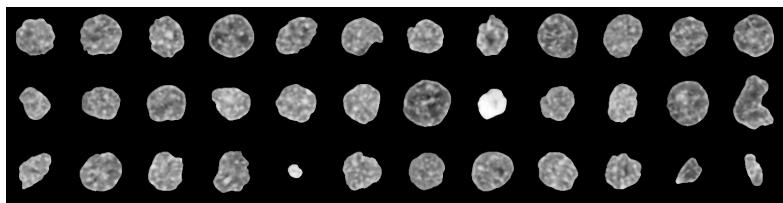
template for class 1 $\varphi^{(1)} = |$ “confound”

$$\mathbb{S}^{(2)} = \left\{ s_j^{(2)} \mid s_j^{(2)} = |\det J g_j| \varphi^{(2)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$$

template for class 2 $\varphi^{(2)} = 2$

A typical learning problem

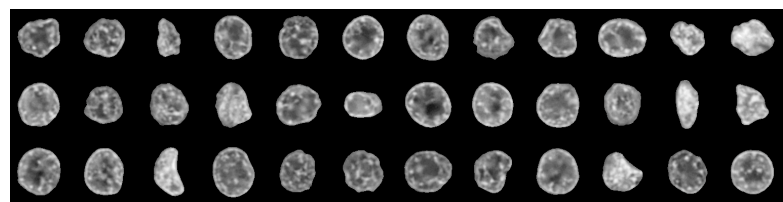
$\mathbb{S}^1$: class 1 (benign cell nuclei)



$$\mathbb{S}^{(1)} = \left\{ s_j^{(1)} \mid s_j^{(1)} = |\det J g_j| \varphi^{(1)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$$

$$\varphi^{(1)} = \text{unknown}$$

$\mathbb{S}^2$: class 2 (malignant)



$$\mathbb{S}^{(2)} = \left\{ s_j^{(2)} \mid s_j^{(2)} = |\det J g_j| \varphi^{(2)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$$

$$\varphi^{(2)} = \text{unknown}$$

$$g_j \in \mathcal{G} \quad \text{unknown}$$

Model for 1D signal classes

$\mathbb{S}^{(1)}$: class for normal ECG heartbeats



$$\mathbb{S}^{(1)} = \{s_j^{(1)} \mid s_j^{(1)} = g'_j \varphi^{(1)} \circ g_j, \forall g_j \in \mathcal{G}\}$$

template for class 1: $\varphi^{(1)}$

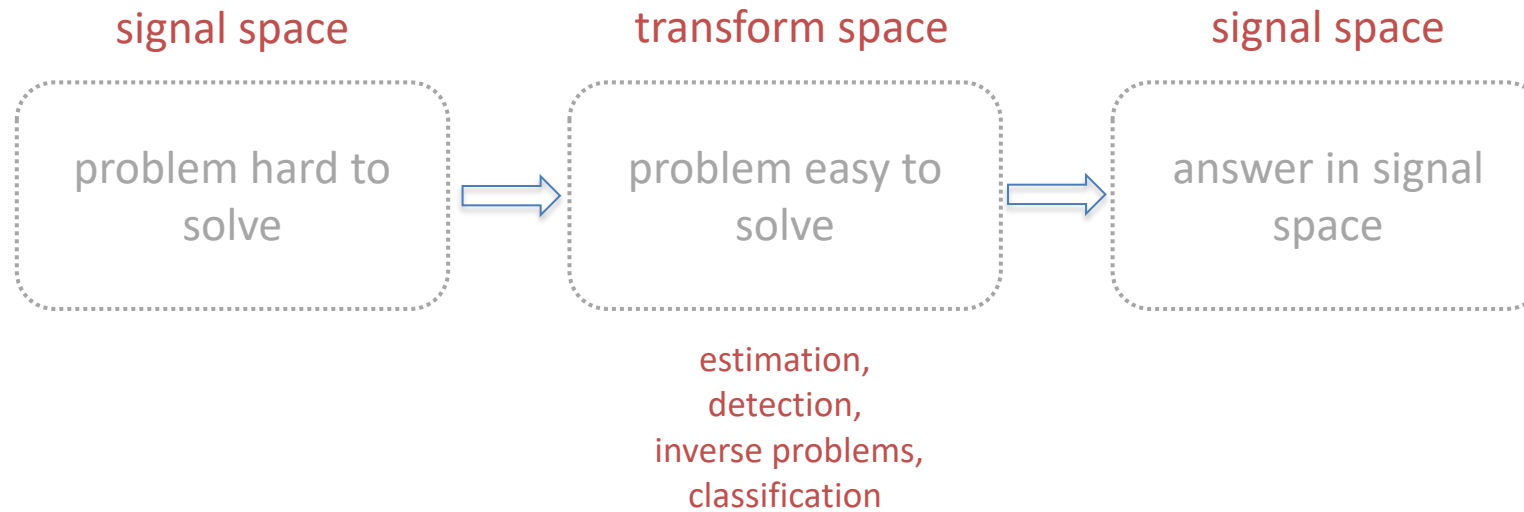
$\mathbb{S}^{(2)}$: class for premature ventricular contraction beats



$$\mathbb{S}^{(2)} = \{s_j^{(2)} \mid s_j^{(2)} = g'_j \varphi^{(2)} \circ g_j, \forall g_j \in \mathcal{G}\}$$

template for class 2: $\varphi^{(2)}$

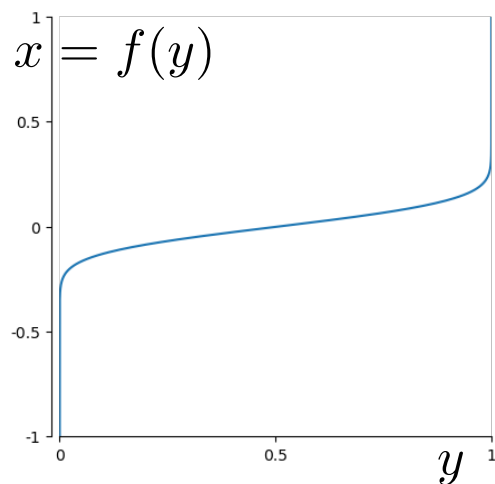
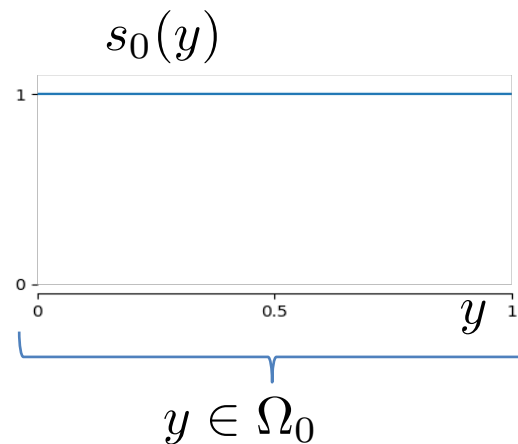
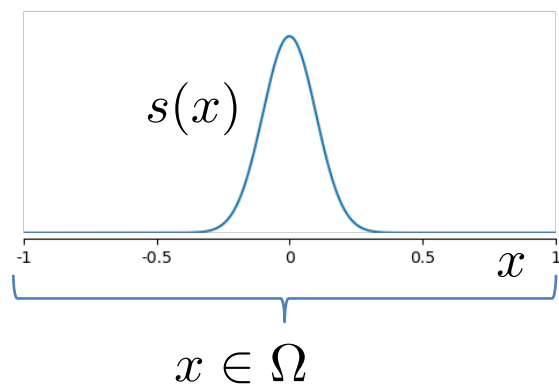
Solution: Transport Transforms



- [Wang, Slepcev, Basu, Ozolek, Rohde, IJCV 2013]
- [Kolouri, Tosun, Ozolek, Rohde, Pattern Recognition 2016]
- [Kolouri, Park, Rohde, IEEE TIP, 2016]
- [Park, Kolouri, Kundu, Rohde, ACHA 18]
- [Rubaiyat et al, IEEE TSP, 20]
- [Aldroubi, Li, Rohde, SaSiDa, 21]
- [Shifat-E-Rabbi et al, Rohde, JMIV 21]
- [Aldroubi et al, AIMS Foundations of Data Science, 22]

Transport transforms

CDT: invertible (nonlinear) signal transform



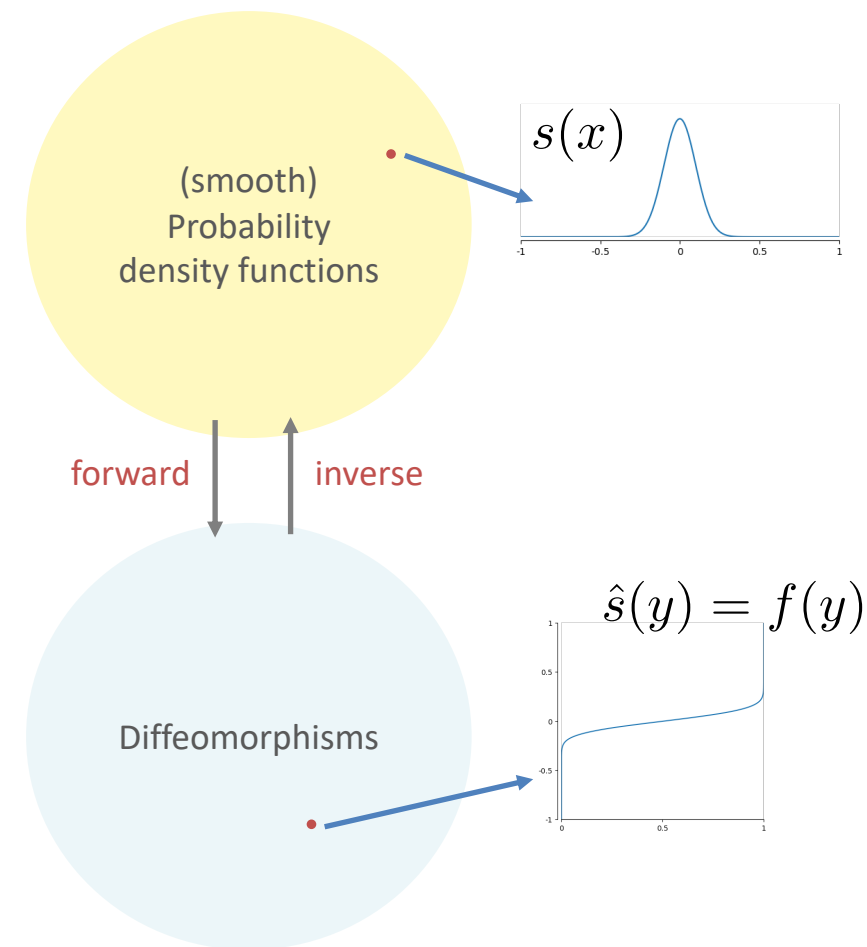
$$f : \Omega_0 \rightarrow \Omega$$

$$f'(y)s(f(y)) = s_0(y)$$

$$S(f(y)) = S_0(y)$$

$$y \in \Omega_0$$

$$\hat{s}(y) = f(y)$$



1-D Transport transform

cumulative distribution transform (CDT)

[Park, Kolouri, Kundu, Rohde, ACHA 2018]

Let $s(x), s_0(x) > 0$ and $\int s(x)dx = \int s_0(x)dx = 1$ (PDFs)

Consider a map $f(x)$, such that

$$\underbrace{\int_{-\infty}^x s_0(u)du}_{\text{antiderivative}} = \underbrace{\int_{-\infty}^{f(x)} s(u)du}_{\text{antiderivative}}$$

antiderivative

$$S_0(x) = S(f(x)) \implies f(x) = S^{-1}(S_0(x))$$

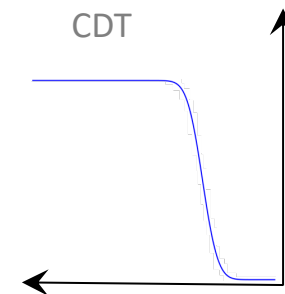
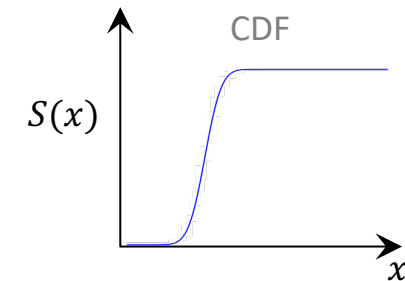
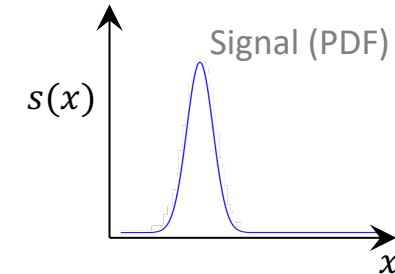
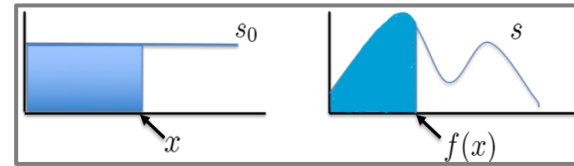
transform of s

Eg.: Let $s_0 = \chi_{[0,1]}$. Then, $S_0(x) = x$ and $f(x) = S^{-1}(x)$.

transform equations

$$\hat{s}(x) := S^{-1}(x) \quad \text{forward}$$

$$s(x) = (\hat{s}^{-1}(x))' \quad \text{inverse}$$



$$\hat{s}(x) = S^{-1}(x)$$

Extension to 2d, 3d: Radon Cumulative distribution transform (R-CDT)

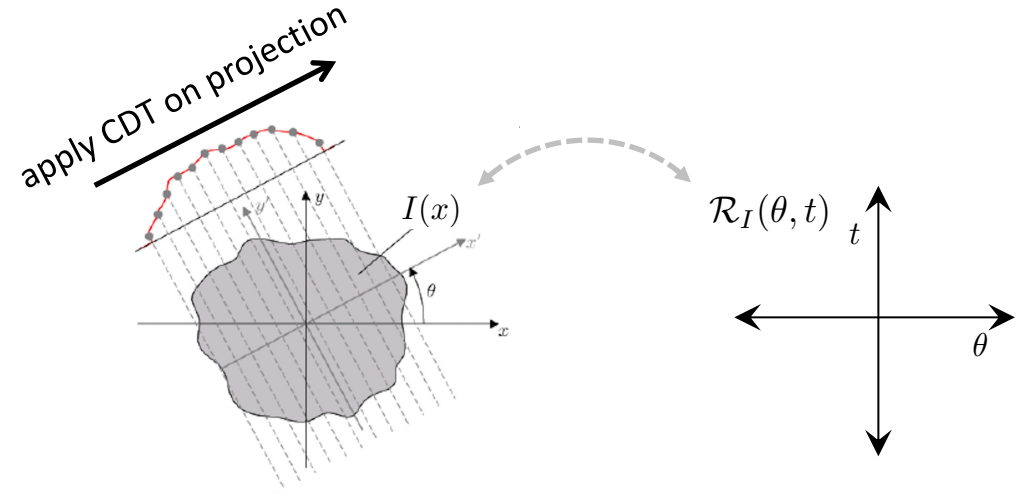
Radon Transform

Forward

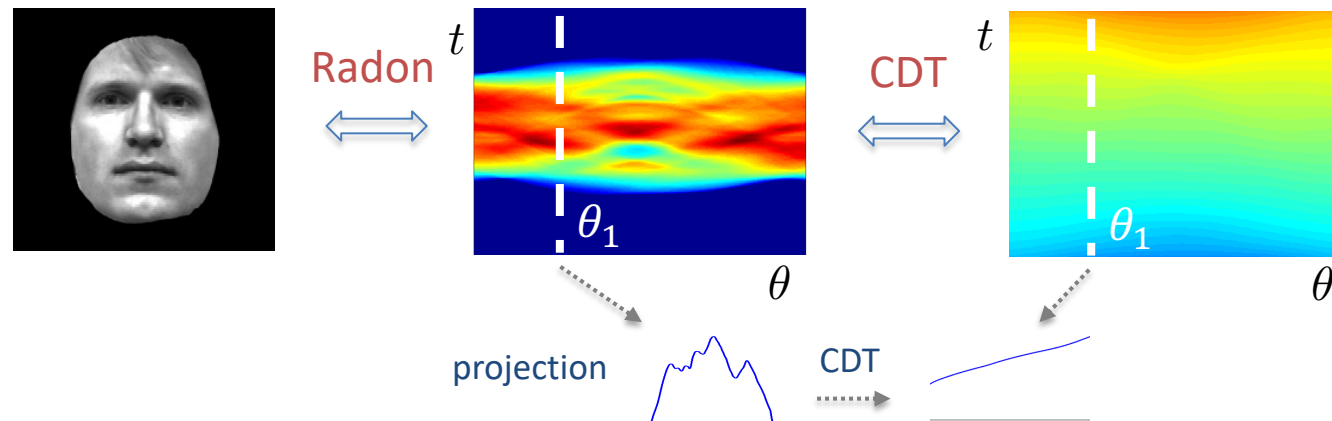
$$\mathcal{R}_I(\theta, t) = \int I(x) \delta(t - \omega \cdot x) dx$$
$$\omega = [\sin \theta, \cos \theta]^T$$

Inverse

$$\mathcal{R}_I^{-1}(x) = \int_{\mathbb{S}^{d-1}} (\mathcal{R}I(\cdot, \theta) * \eta(\cdot)) \circ (x \cdot \theta) d\theta$$



Radon Cumulative Distribution Transform

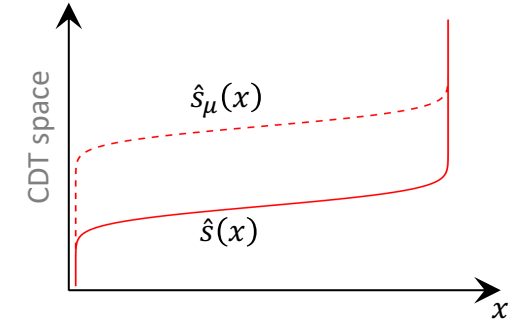
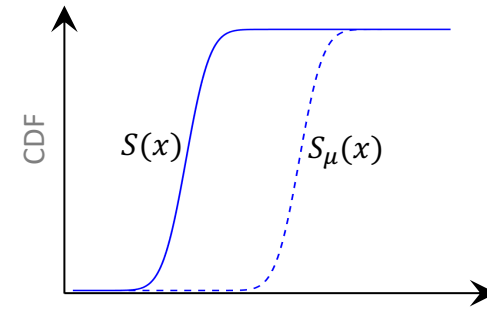
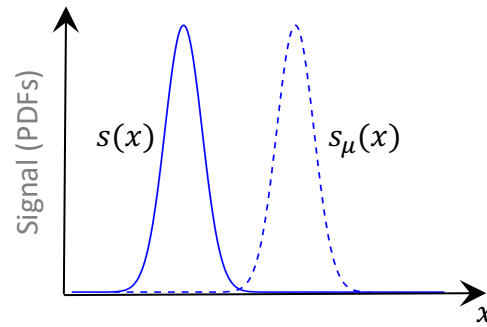


CDT Properties

Translation

$$s_\mu(x) = s(x - \mu)$$

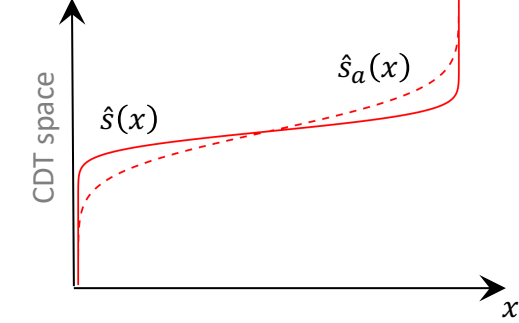
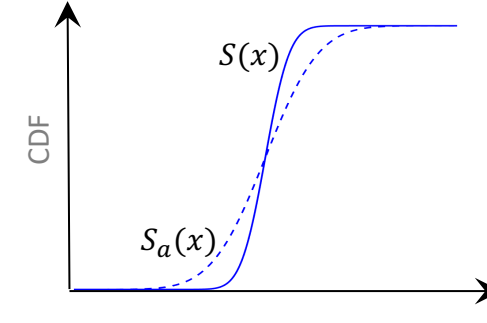
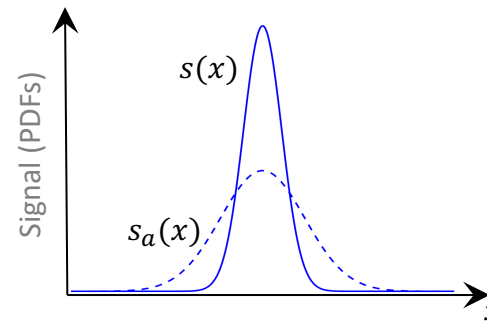
$$\hat{s}_\mu(x) = \hat{s}(x) + \mu$$



Scaling

$$s_a(x) = a s(ax)$$

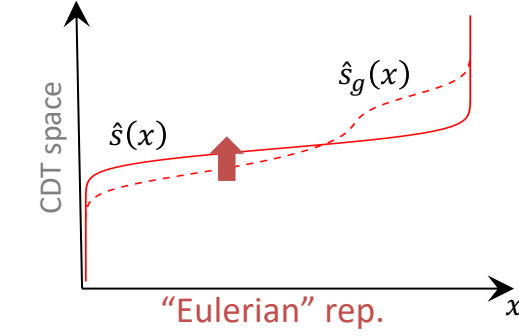
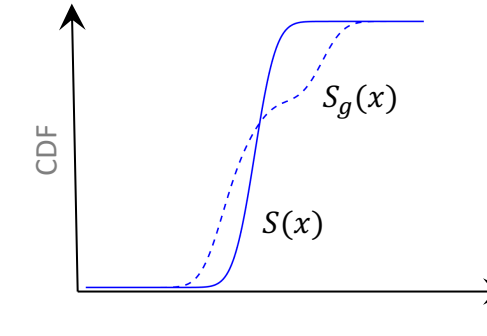
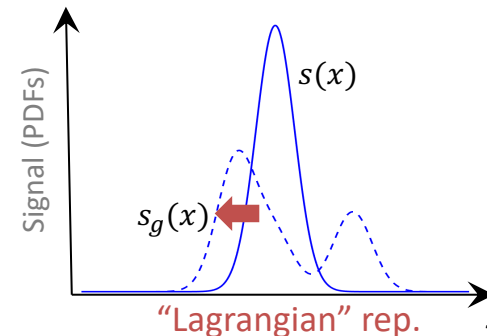
$$\hat{s}_a(x) = \frac{\hat{s}(x)}{a}$$



Composition

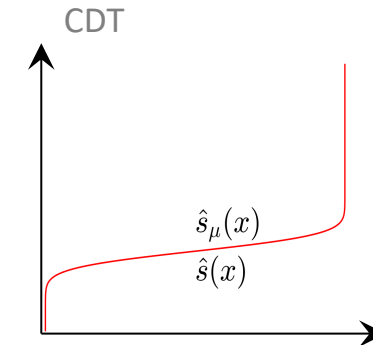
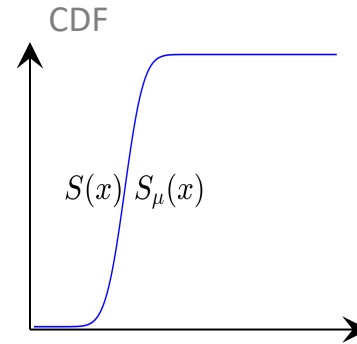
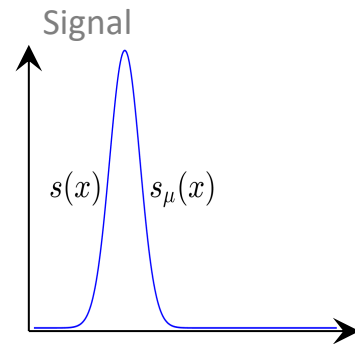
$$s_g(x) = g'(x)s(g(x))$$

$$\hat{s}_g(x) = g^{-1}(\hat{s}(x))$$

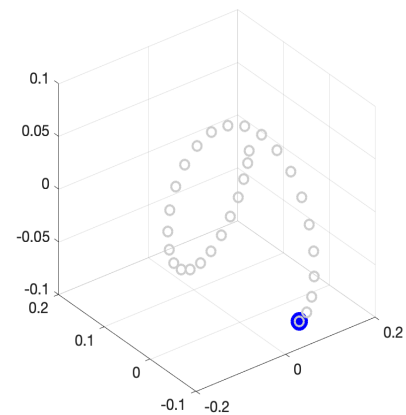


Data Geometry

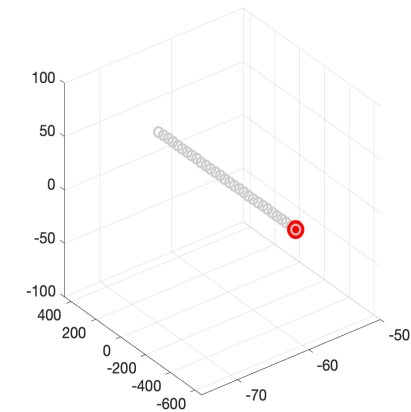
Consider the data set generated by a signal and all of its translates



PCA (3 components) of dataset



nonlinear/nonconvex



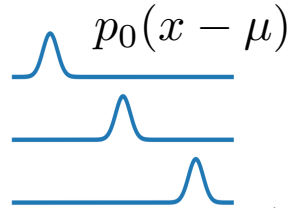
linear/convex

Signal classes: generative model

signal space

Class $\mathbb{P}$

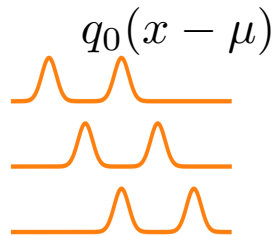
template 1 p_0



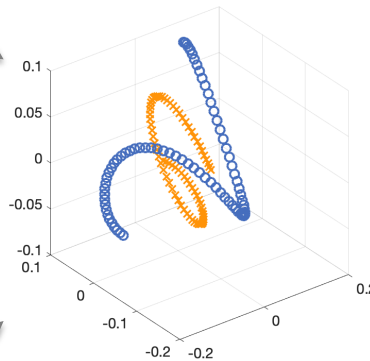
$$\mathbb{P} = \{p_g | p_g(x) = g'(x)p_0(g(x))\}$$

Class $\mathbb{Q}$

template 2 q_0



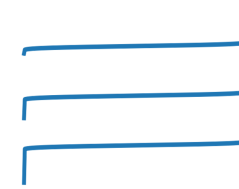
$$\mathbb{Q} = \{q_g | q_g(x) = g'(x)q_0(g(x))\}$$



low dimensional
projection

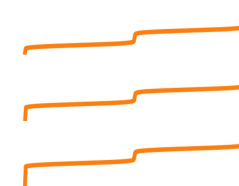
transform space

$\hat{\mathbb{P}}$

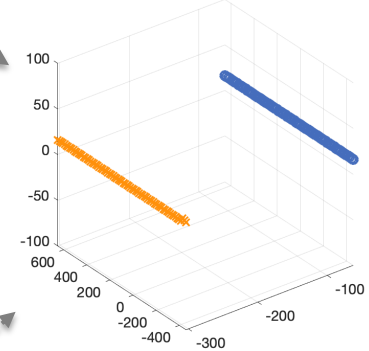


$$\hat{p}_g = \hat{p} + \mu$$

$\hat{\mathbb{Q}}$



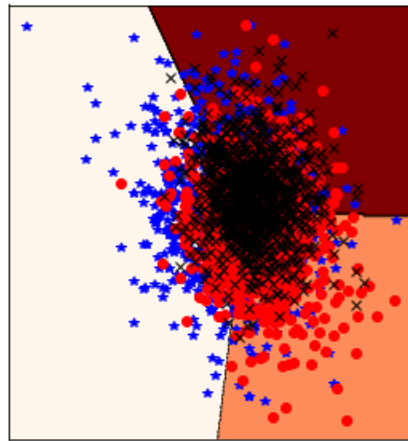
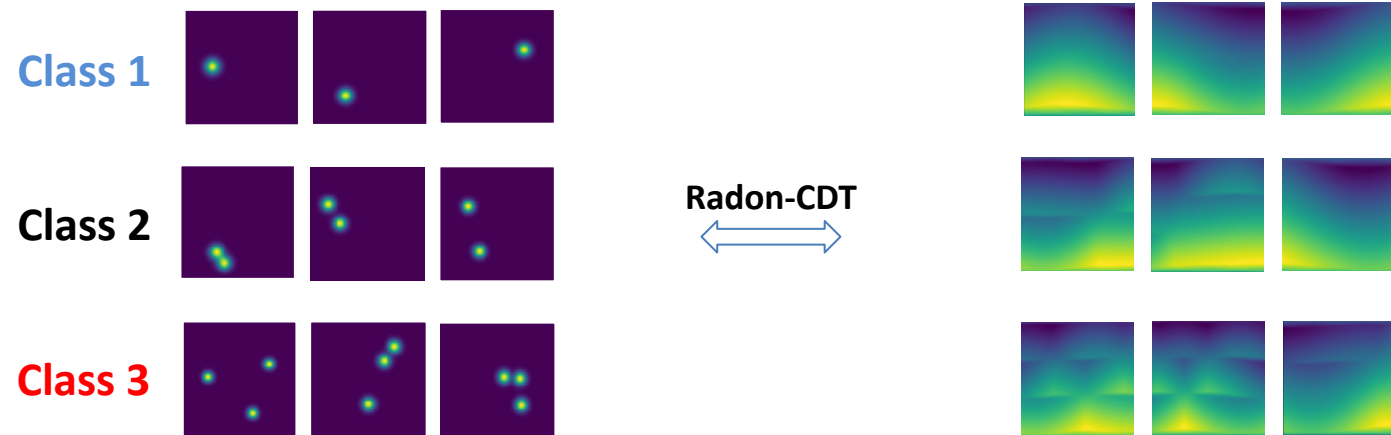
$$\hat{q}_g = \hat{q} + \mu$$



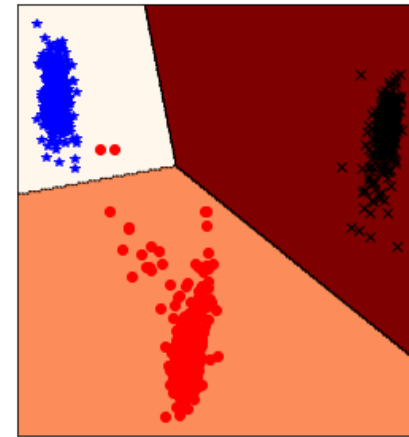
low dimensional
projection

“confound” $g \in \mathcal{C}$ e.g.: translation $g(x) = x - \mu$

2D Example



LDA subspace of original data



LDA subspace of transformed data

CDT: linear separation theorem

Consider signal classes:

$$\mathbb{P} = \{p_g : g \in \mathcal{C}\} \text{ and } \mathbb{Q} = \{q_g : g \in \mathcal{C}\}$$

$$\text{where } p_g(x) = g'(x)p_0(g(x)) \quad \mathbb{P} \cap \mathbb{Q} = \emptyset$$

$$q_g(x) = g'(x)q_0(g(x))$$

Theorem:

$\hat{\mathbb{P}}, \hat{\mathbb{Q}}$ will be *convex*

iff $\mathcal{C}^{-1}$ is convex.

for any reference s_0
does not require knowledge of p_0, q_0

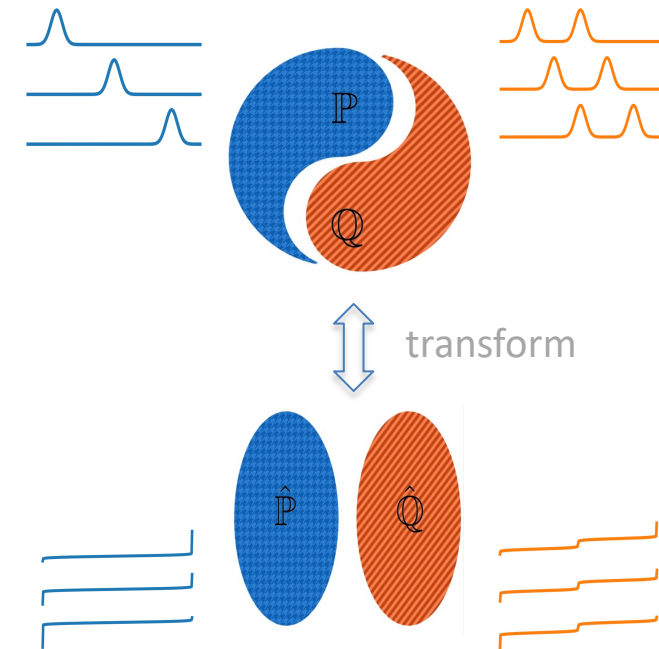
Corollary:

$\hat{\mathbb{P}}, \hat{\mathbb{Q}}$ linearly separable

if $\mathcal{C}^{-1}$ is convex.

To see this: $\hat{\mathbb{P}} = \{g^{-1}(\hat{p}(y)) | g^{-1} \in \mathcal{C}^{-1}\}$

$\hat{\mathbb{Q}} = \{g^{-1}(\hat{q}(y)) | g^{-1} \in \mathcal{C}^{-1}\}$ $\Rightarrow$ convex iff $\mathcal{C}^{-1}$ convex



[Park, Kolouri, Kundu, Rohde, ACHA 18]

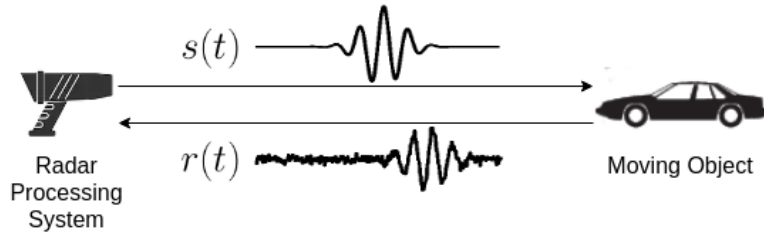
[Aldroubi, Li, Rohde, SaSiDa, 21]

[Shifat-E-Rabbi, ..., Rohde, JMIV 21]

[Aldroubi et al, AIMS Foundations of Data Science, 22]

Applications

Parametric signal estimation



Static object: $r(t) = s(t - \tau) + \eta(t)$

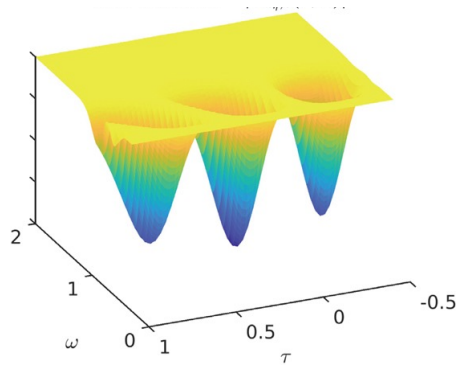
$$g_p(t) = \omega t - \tau$$

Moving object: $r(t) = s(\omega t - \tau) + \eta(t)$

Traditional approach:

$$A_{r,s}(\tau, \omega) = \sqrt{\omega} \int r(t) s(\omega t - \tau) dt$$

$$\arg \min_{\tau, \omega} -|A_{r,s}(\tau, \omega)|$$

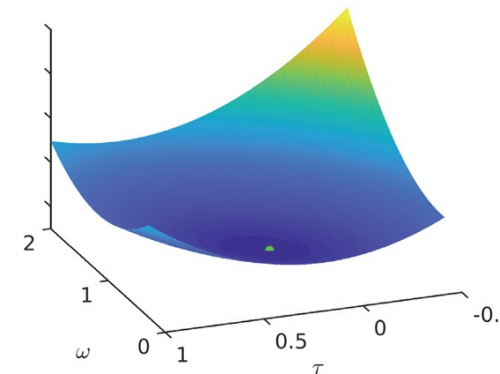


computationally expensive
global optimization required

Wasserstein minimization

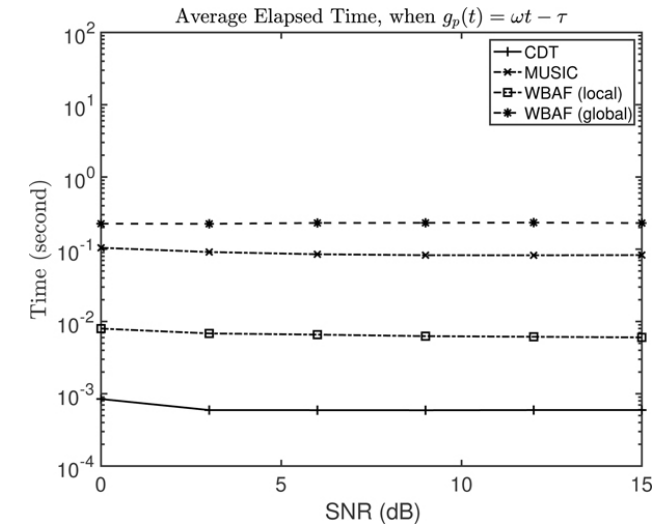
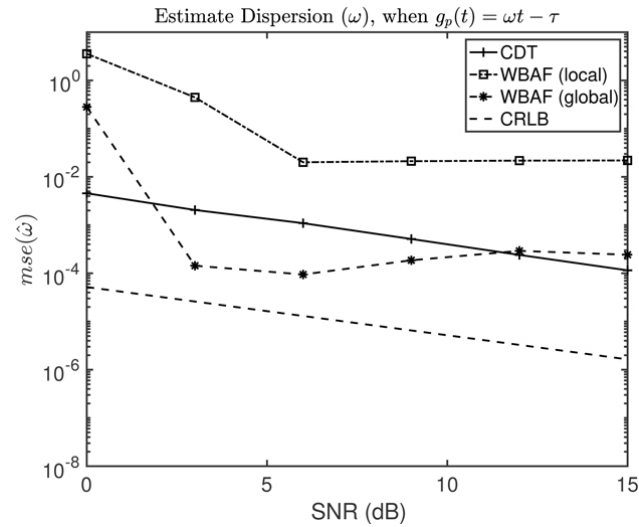
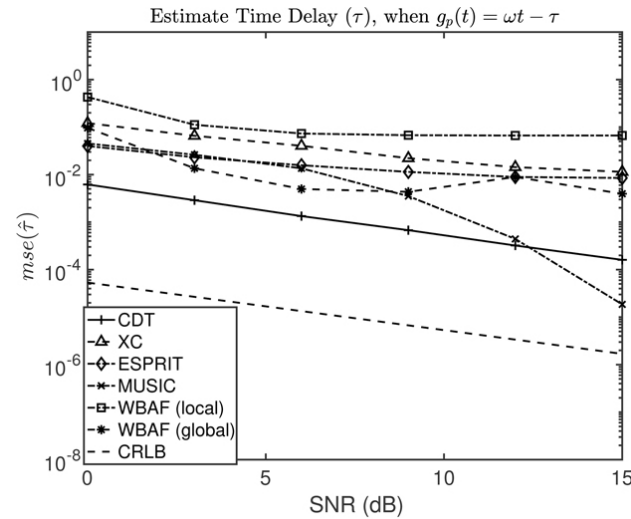
$$W^2(r, s) = \|\omega \hat{r} - \tau - \hat{s}\|^2$$

$$\arg \min_{\tau, \omega} \|\omega \hat{r} - \tau - \hat{s}\|^2$$



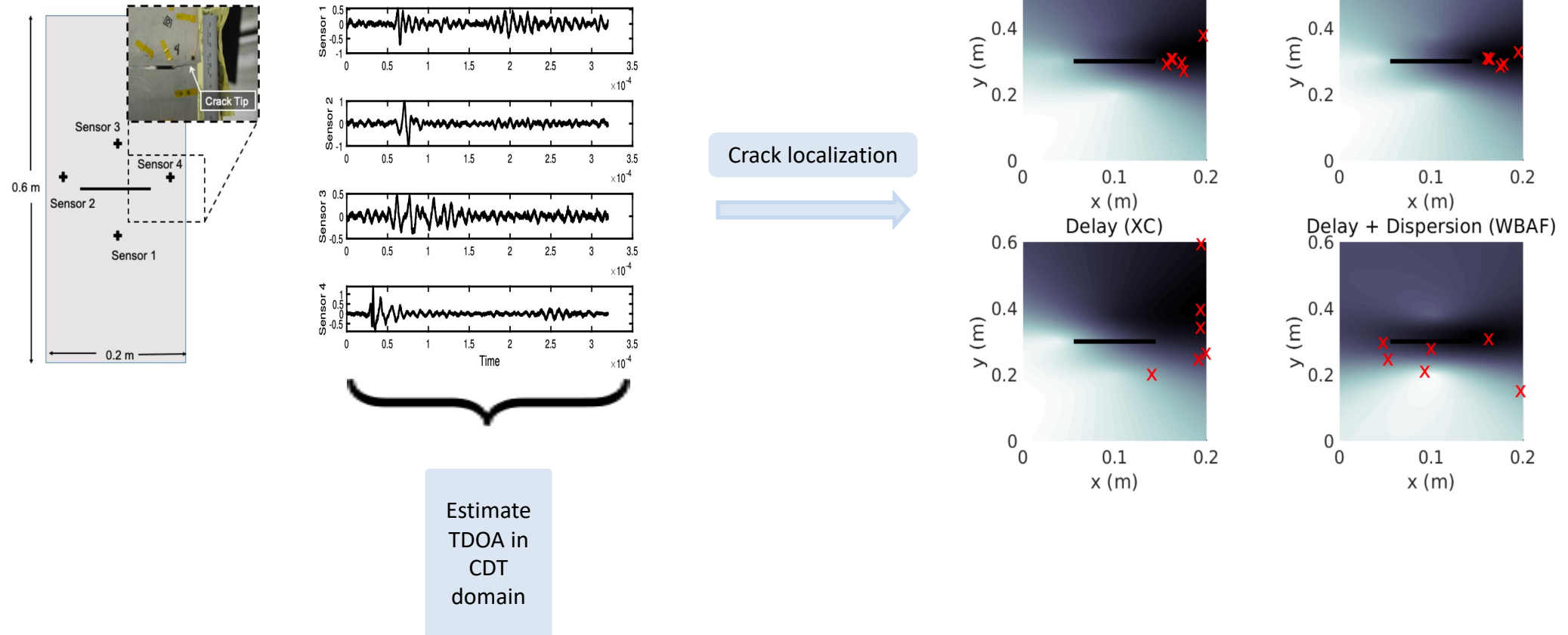
linear least squares
cheap to compute

Parametric signal estimation



orders of magnitude cheaper to compute

Parametric signal estimation in structural health monitoring



Model-based inverse problems

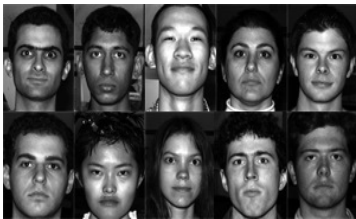
Enhancing an image

Find model parameters that best match data

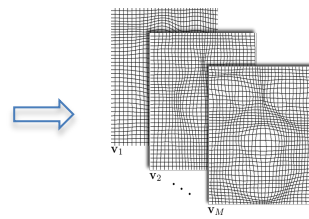


Modeling phase

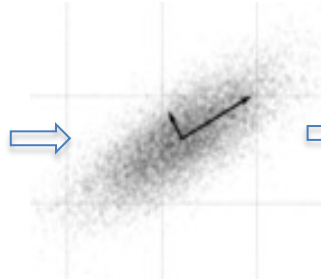
sample database



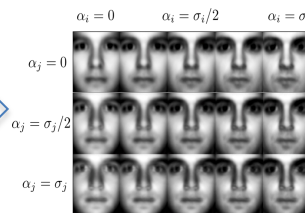
transform



PCA



model



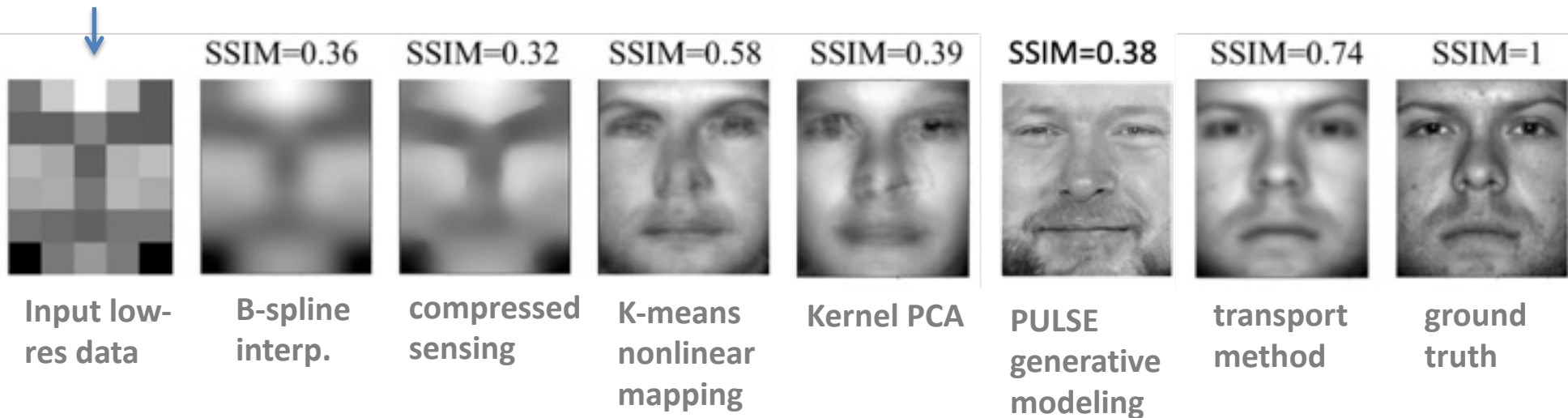
Model: $M_\alpha = D_{f_\alpha}(x)I_0(f_\alpha(x)) \quad f_\alpha(x) = \sum_k \alpha_k \phi_k(x)$

Fit: $\min_\alpha \|I - \underset{\text{degradation}}{V} M_\alpha\|^2$

low-res data

Transport PCA trained on high res database

5x6 pixels!



Applications: classification

Problem statement (supervised learning)

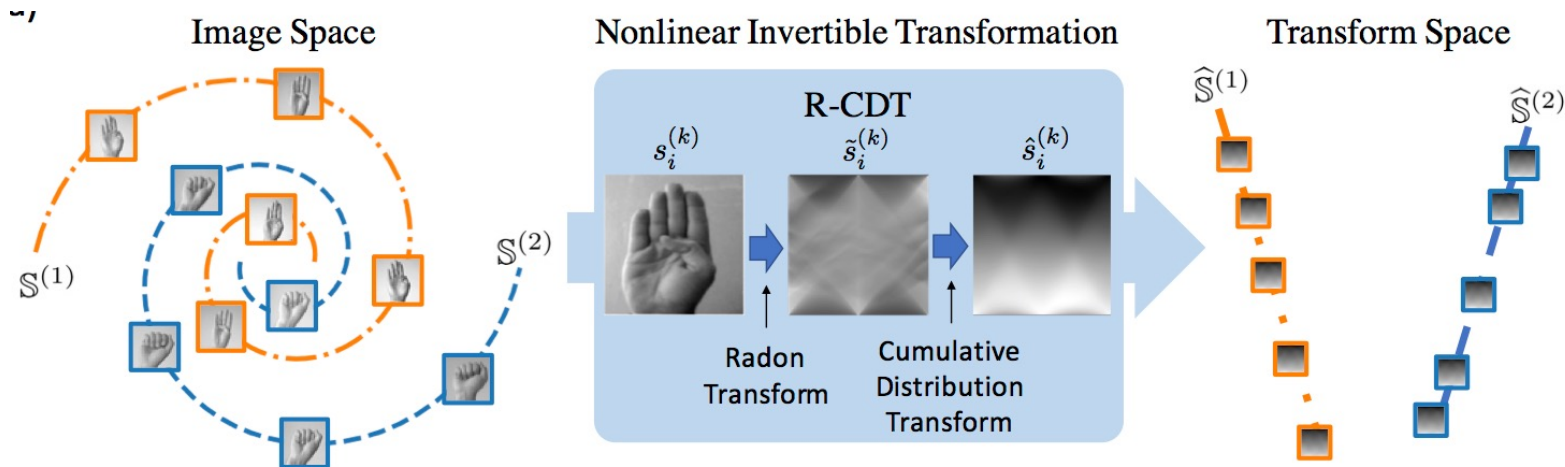
Training: given sample signals/images from different classes

$$\{s_1^{(1)}, s_2^{(1)}, \dots\} \quad s_j^{(k)} \in \mathbb{S}^{(k)} = \left\{ s_j^{(k)} \mid s_j^{(k)} = |\det J g_j| \varphi^{(k)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$$

$$\{s_1^{(2)}, s_2^{(2)}, \dots\} \quad \varphi^{(k)} \text{ unknown}$$
$$g_j \in \mathcal{G} \text{ unknown}$$

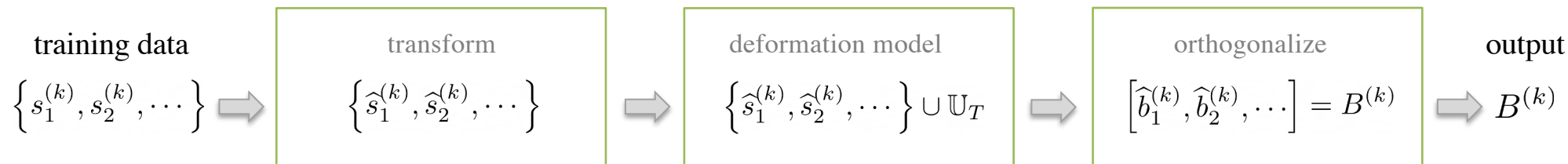
Testing: find the class that a test sample s originated from.

Solution overview

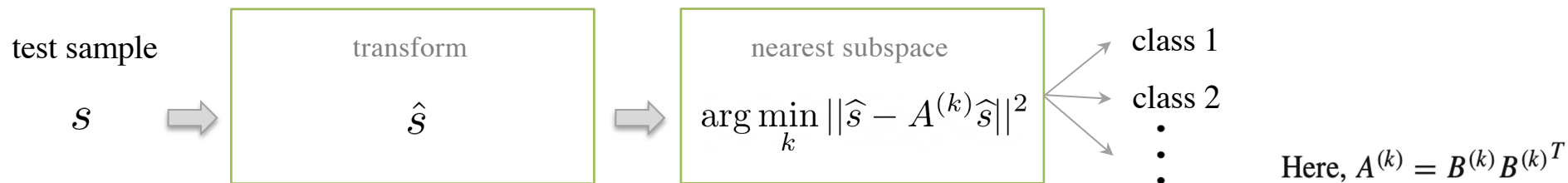


RCDT – nearest subspace

Training: estimating basis vectors for subspaces corresponding to each class



Testing : predicting the test sample as belonging to the class corresponding to the nearest subspace



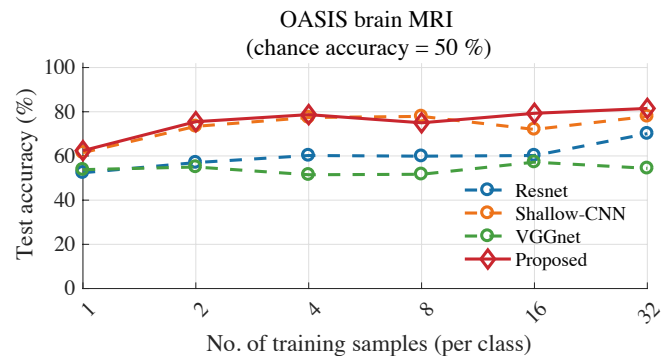
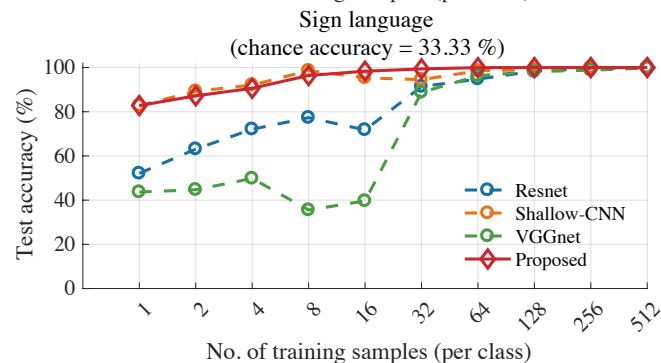
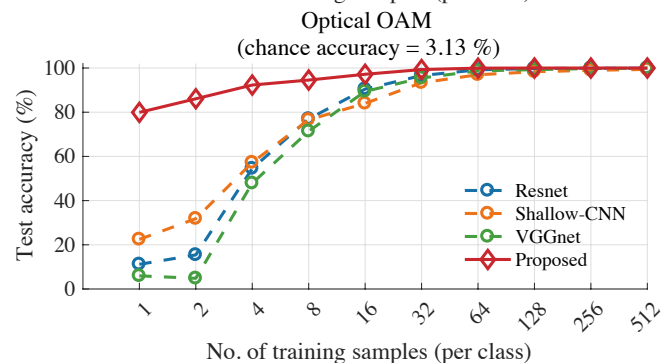
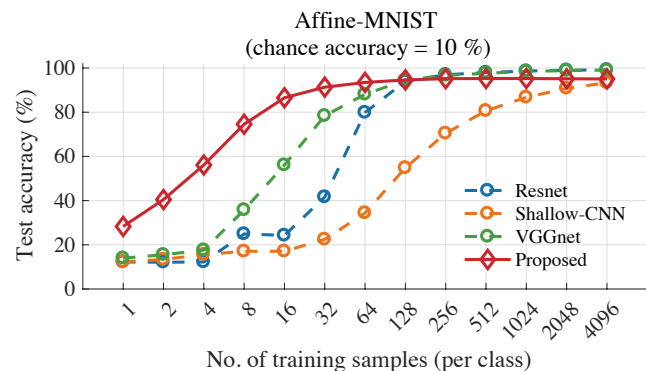
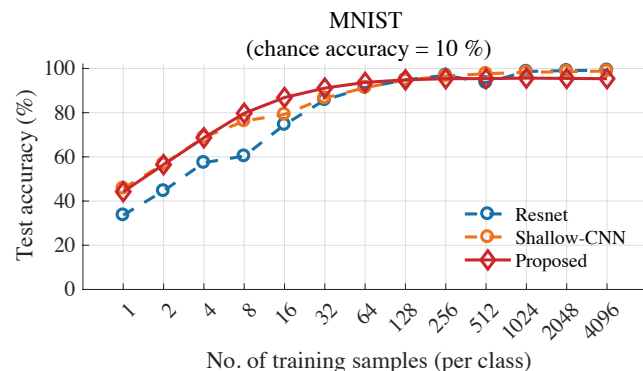
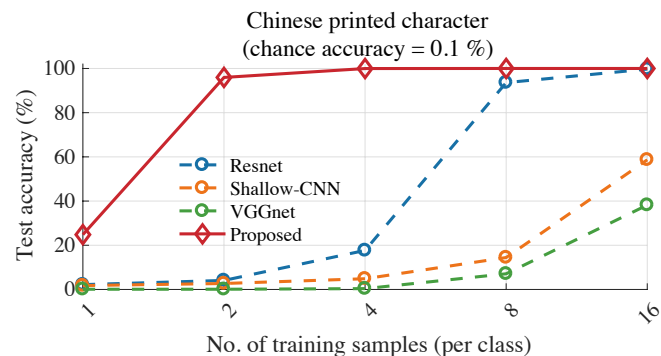
Translation $\mathbb{U}_T = \{u_T^{(1)}(t, \theta), u_T^{(2)}(t, \theta)\}$, with $u_T^{(1)}(t, \theta) = \cos \theta$ and $u_T^{(2)}(t, \theta) = \sin \theta$
Isotropic scaling $\mathbb{U}_D = \emptyset$

Two important aspects of the method:

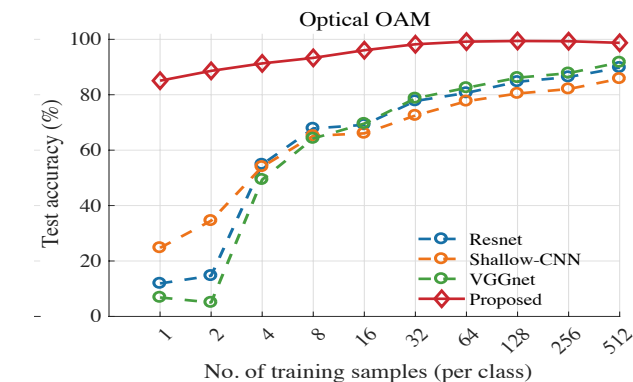
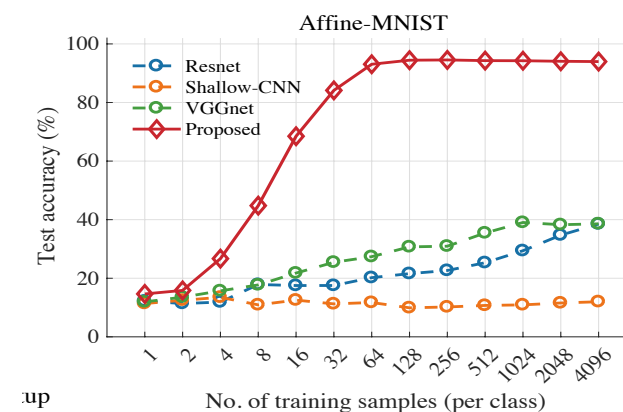
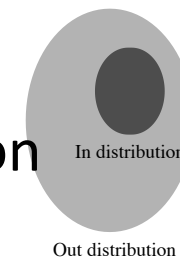
1. The method can learn from datasets
2. The method can learn from mathematically prescribed sets without explicitly using the training data

Results and comparisons with deep learning

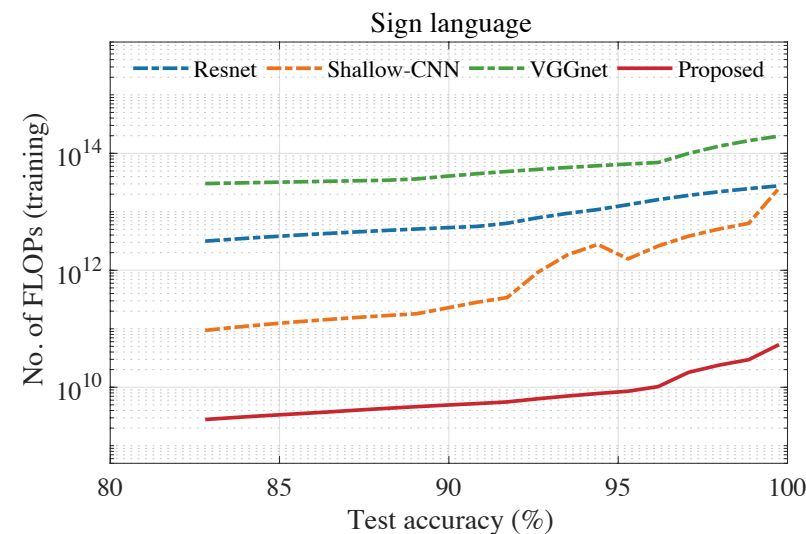
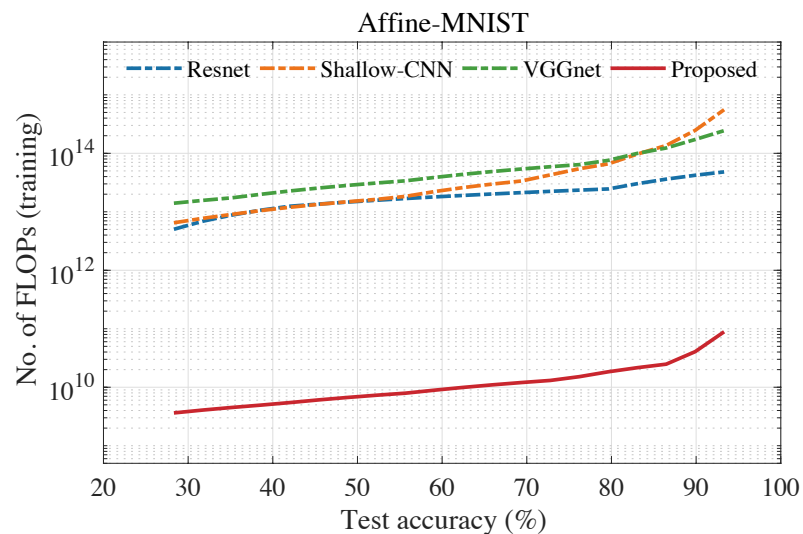
[Shifat-E-Rabbi et al, JMIV 2021]



Out of distribution testing



Results and comparisons with deep learning



Limitations

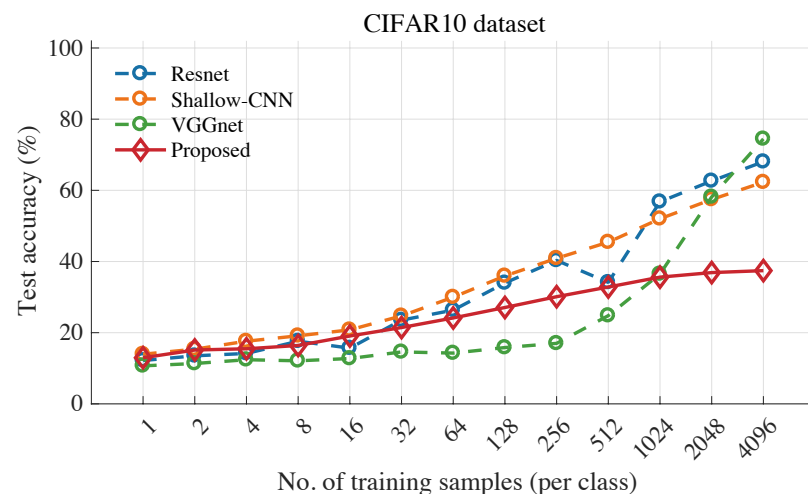
$$\mathbb{P} = \{p_g : g \in \mathcal{C}\} \quad \mathbb{Q} = \{q_g : g \in \mathcal{C}\}$$

where

$$p_g(x) = g'(x)p_0(g(x))$$

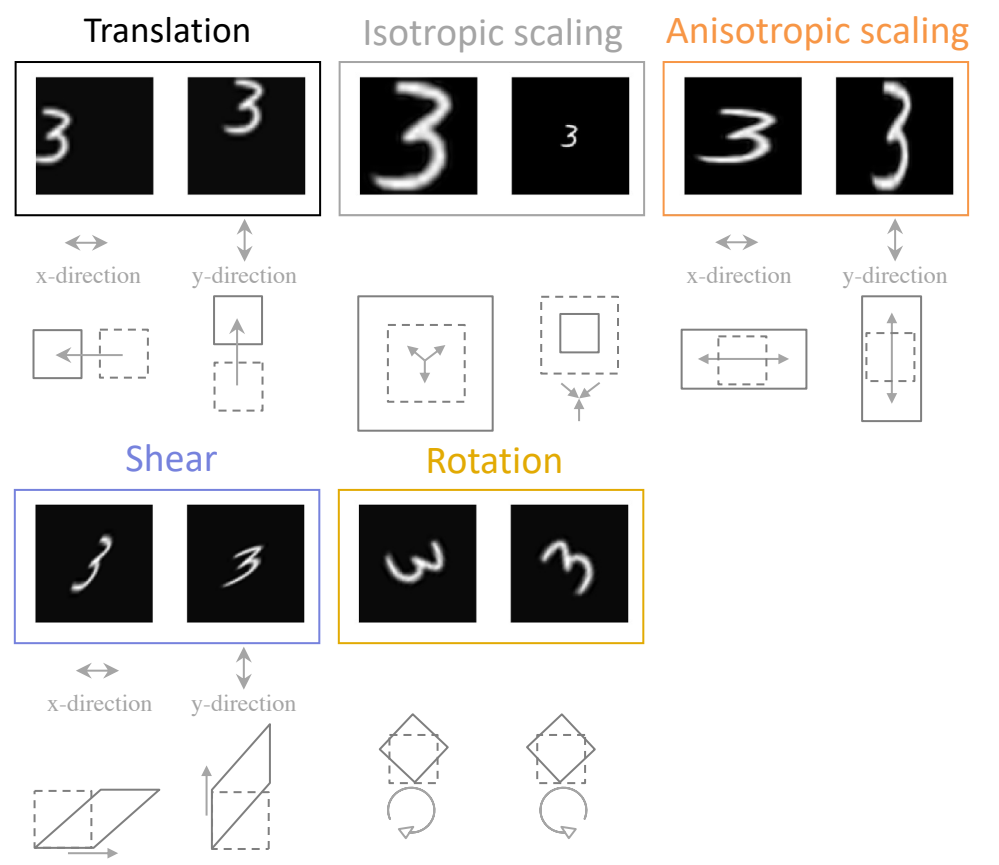
$$q_g(x) = g'(x)q_0(g(x))$$

It doesn't seem to work as well for
general object detection



Invariance encoding

Aim: Can we mathematically model invariances in data?

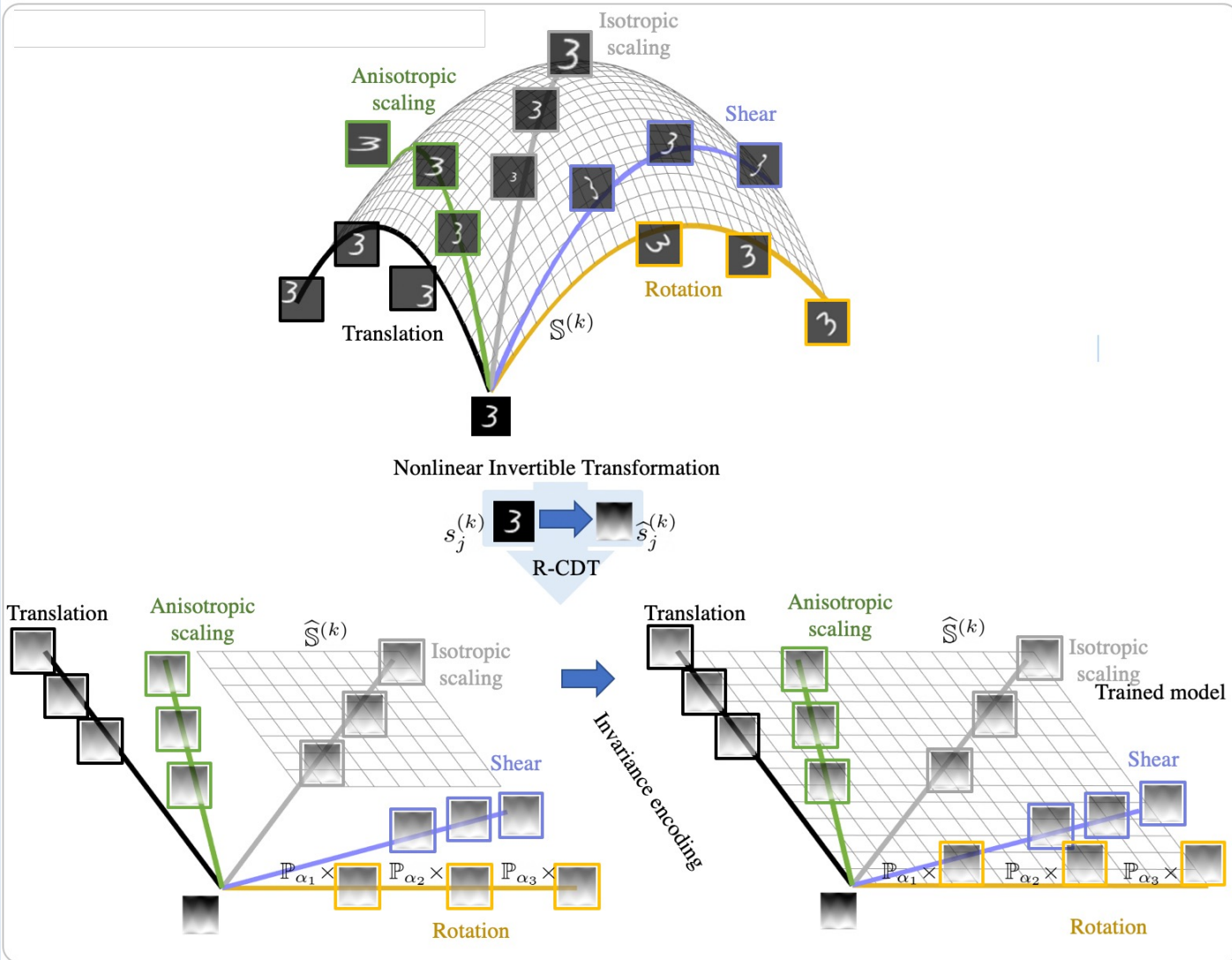


$\{s_1^{(1)}, s_2^{(1)}, \dots\} \quad \{s_1^{(2)}, s_2^{(2)}, \dots\}$

$s_j^{(k)} \in \mathbb{S}^{(k)} = \left\{ s_j^{(k)} \mid s_j^{(k)} = |\det J g_j| \varphi^{(k)} \circ g_j, \forall g_j \in \mathcal{G} \right\}$

$\varphi^{(k)}$ unknown $g_j \in \mathcal{G}$ unknown + affine

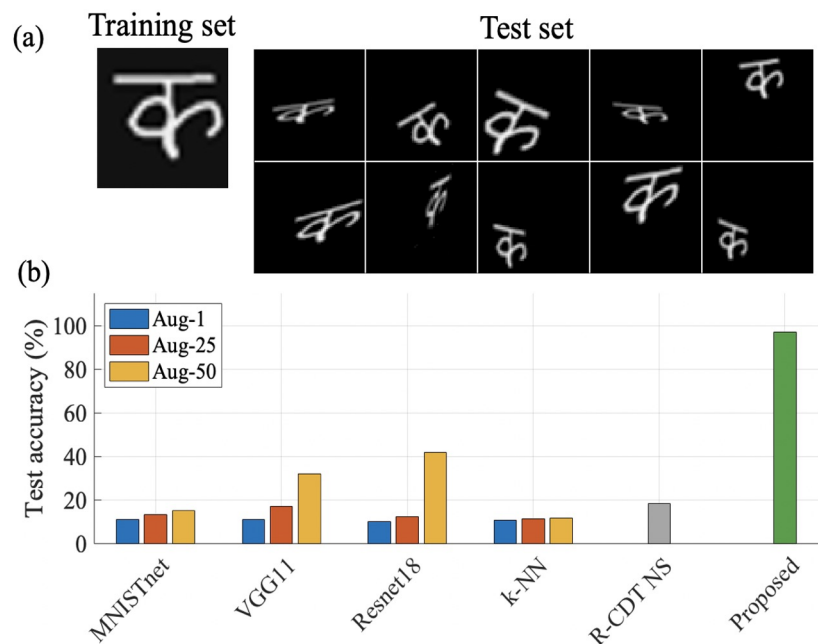
Solution overview:



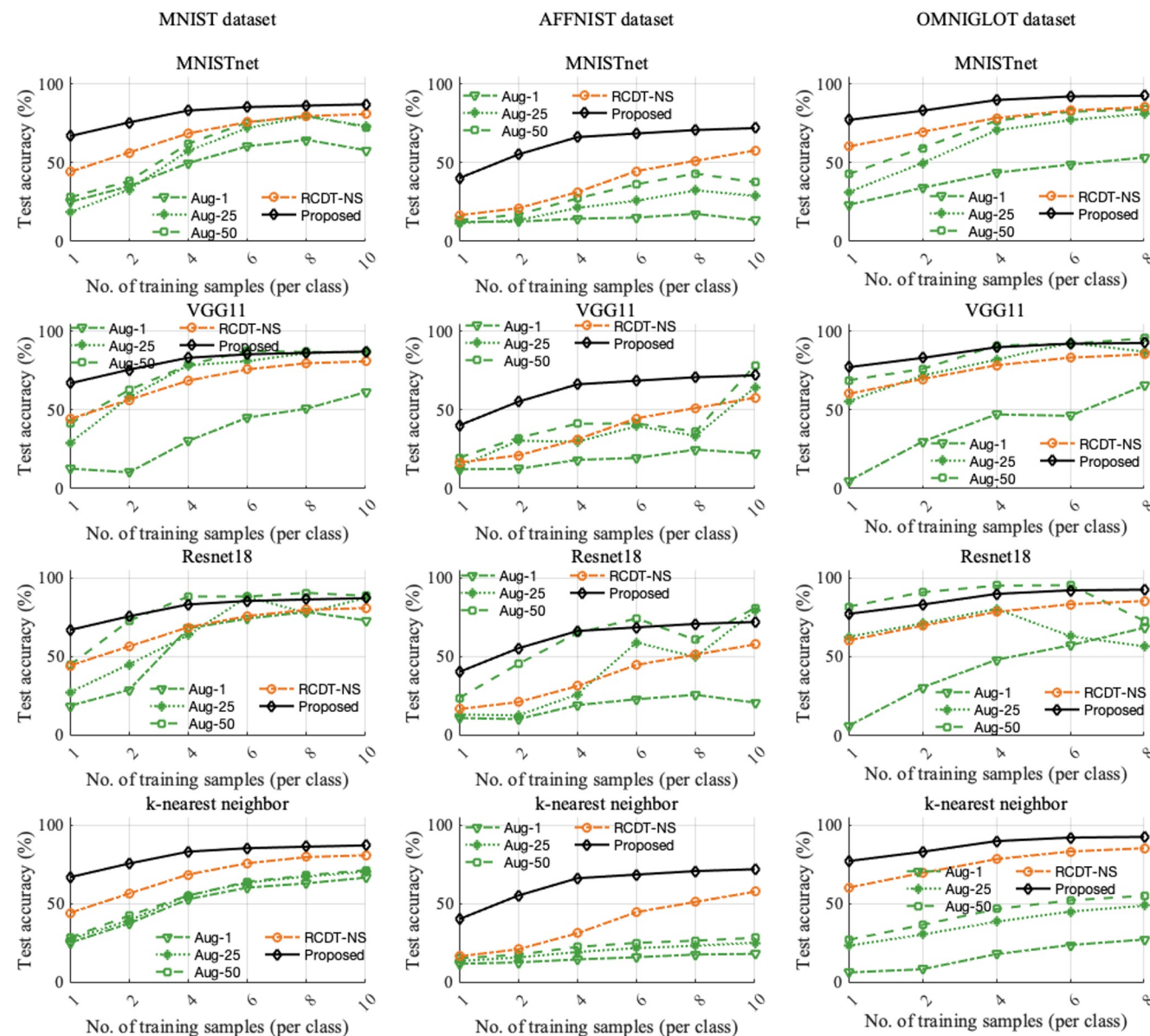
Results and comparisons with deep learning

[Shifat-E-Rabbi et al, arxiv 2022]

Synthetic data



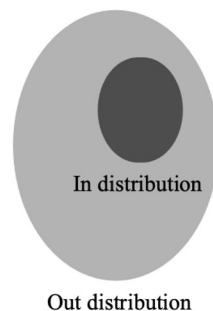
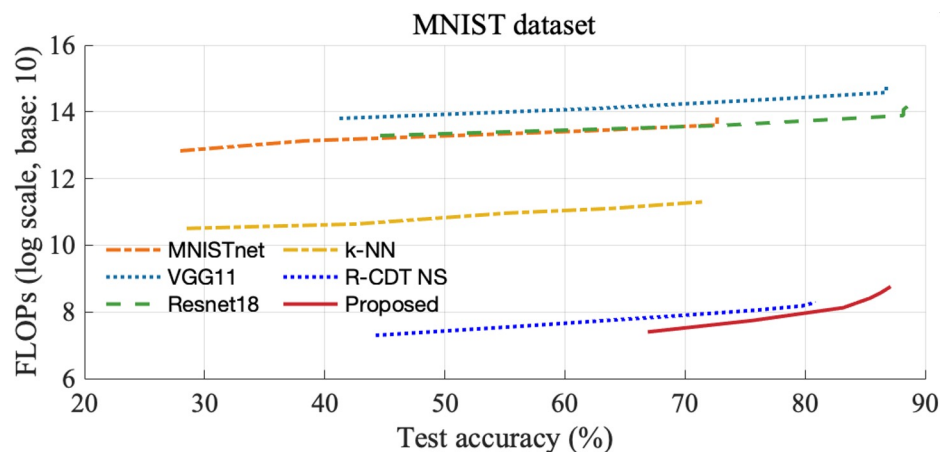
Real data



Results and comparisons with deep learning

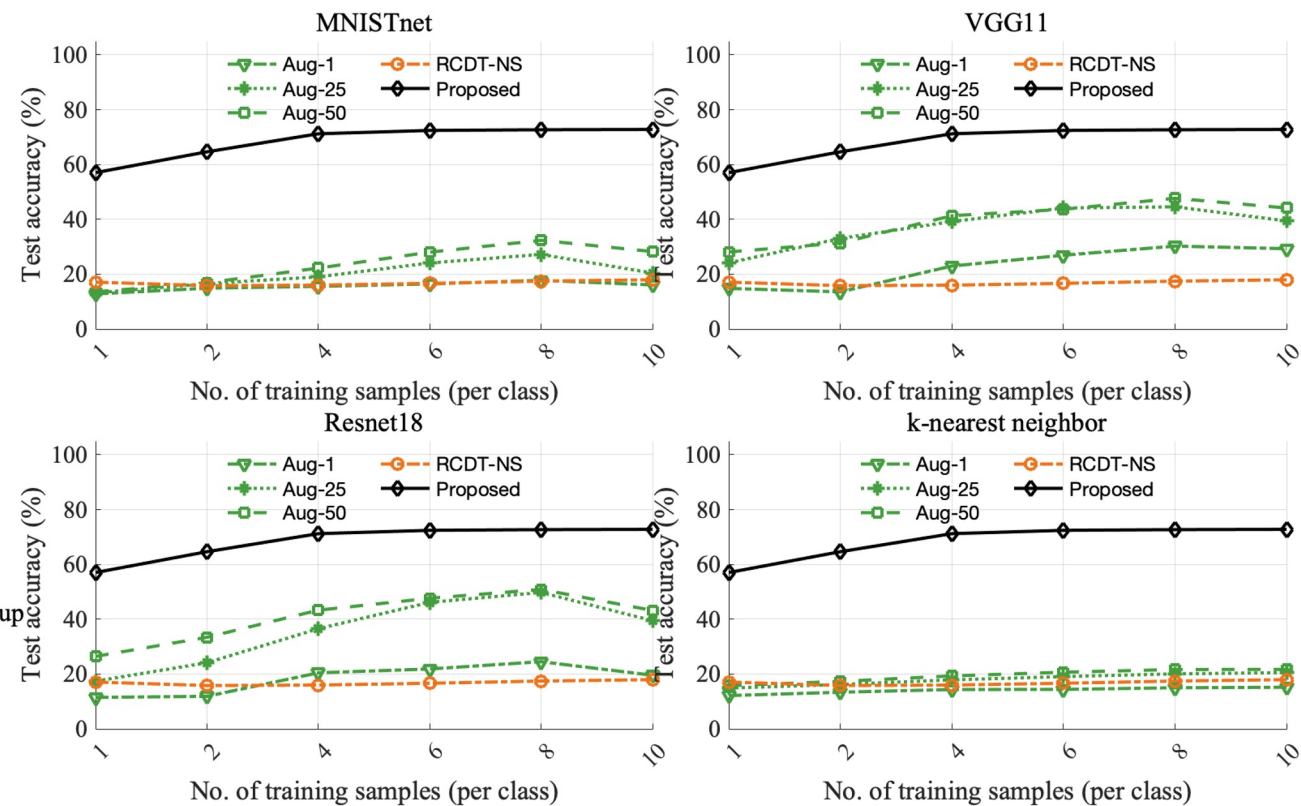
[Shifat-E-Rabbi et al, arxiv 2022]

Computational complexity



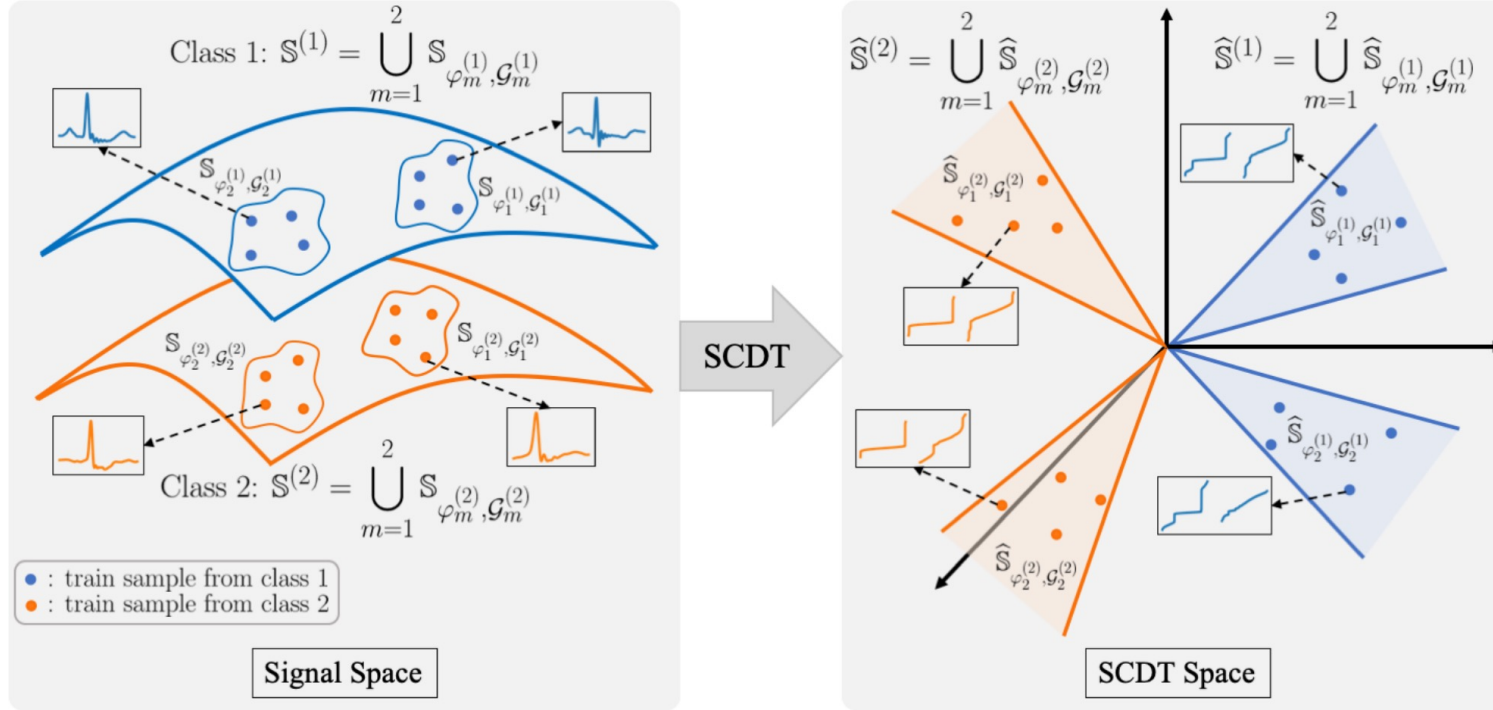
Out of distribution setup

Out-of-distribution experiment



End-to-End Time Series Classification [Rubaiyat et al, ArXiv 2022]

Generative Model:



$$\mathbb{S}^{(c)} = \bigcup_{m=1}^{M_c} \mathbb{S}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}},$$

$$\mathbb{S}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}} = \left\{ s_{j,m}^{(c)} \mid s_{j,m}^{(c)} = g_j' \varphi_m^{(c)} \circ g_j, g_j' > 0, g_j \in \mathcal{G}_m^{(c)} \right\},$$

$$\left(\mathcal{G}_m^{(c)} \right)^{-1} = \left\{ \sum_{i=1}^k \alpha_i f_{i,m}^{(c)}, \alpha_i \geq 0 \right\}$$

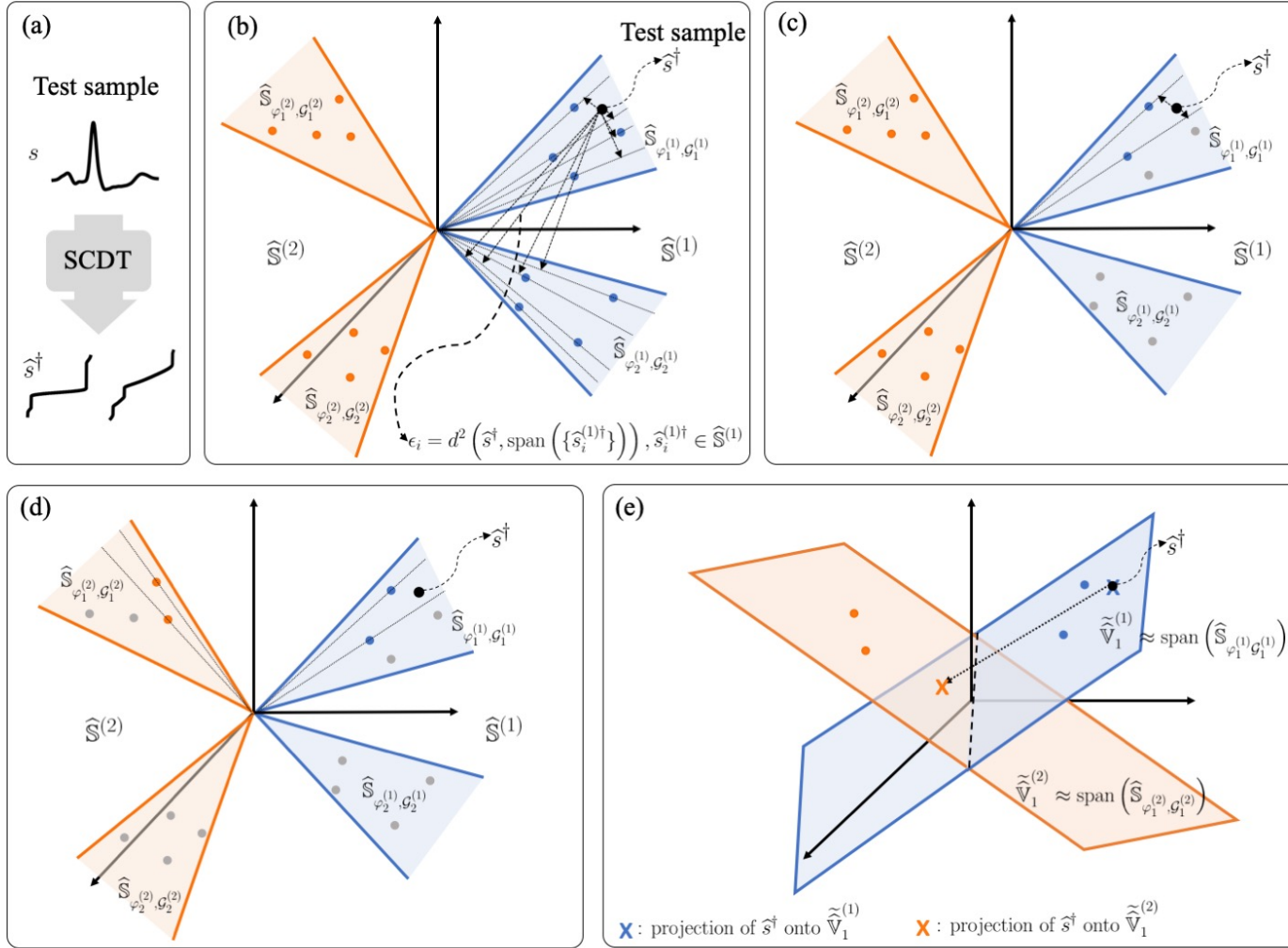
$$\hat{\mathbb{S}}^{(c)} = \bigcup_{m=1}^{M_c} \hat{\mathbb{S}}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}},$$

$$\hat{\mathbb{S}}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}} = \left\{ \hat{s}_{j,m}^{(c)} \mid \hat{s}_{j,m}^{(c)} = g_j^{-1} \circ \hat{\varphi}_m^{(c)}, g_j \in \mathcal{G}_m^{(c)} \right\},$$

$$\left(\mathcal{G}_m^{(c)} \right)^{-1} = \left\{ \sum_{i=1}^k \alpha_i f_{i,m}^{(c)}, \alpha_i \geq 0 \right\}$$

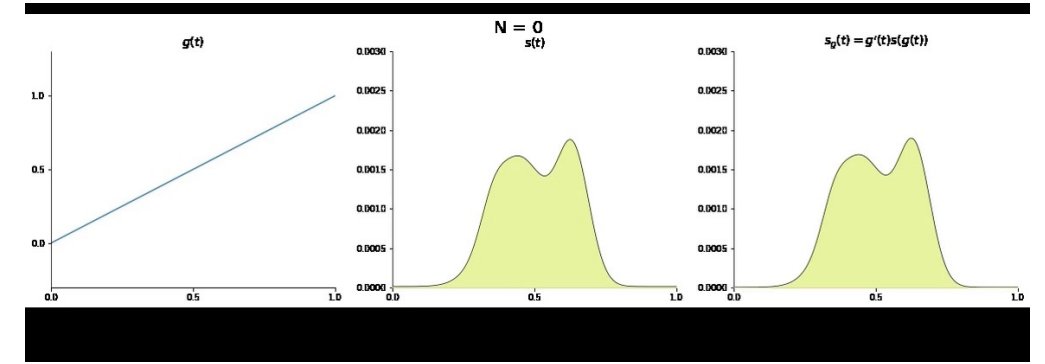
End-to-End Time Series Classification [Rubaiyat et al, ArXiv 2022]

NLS algorithm:

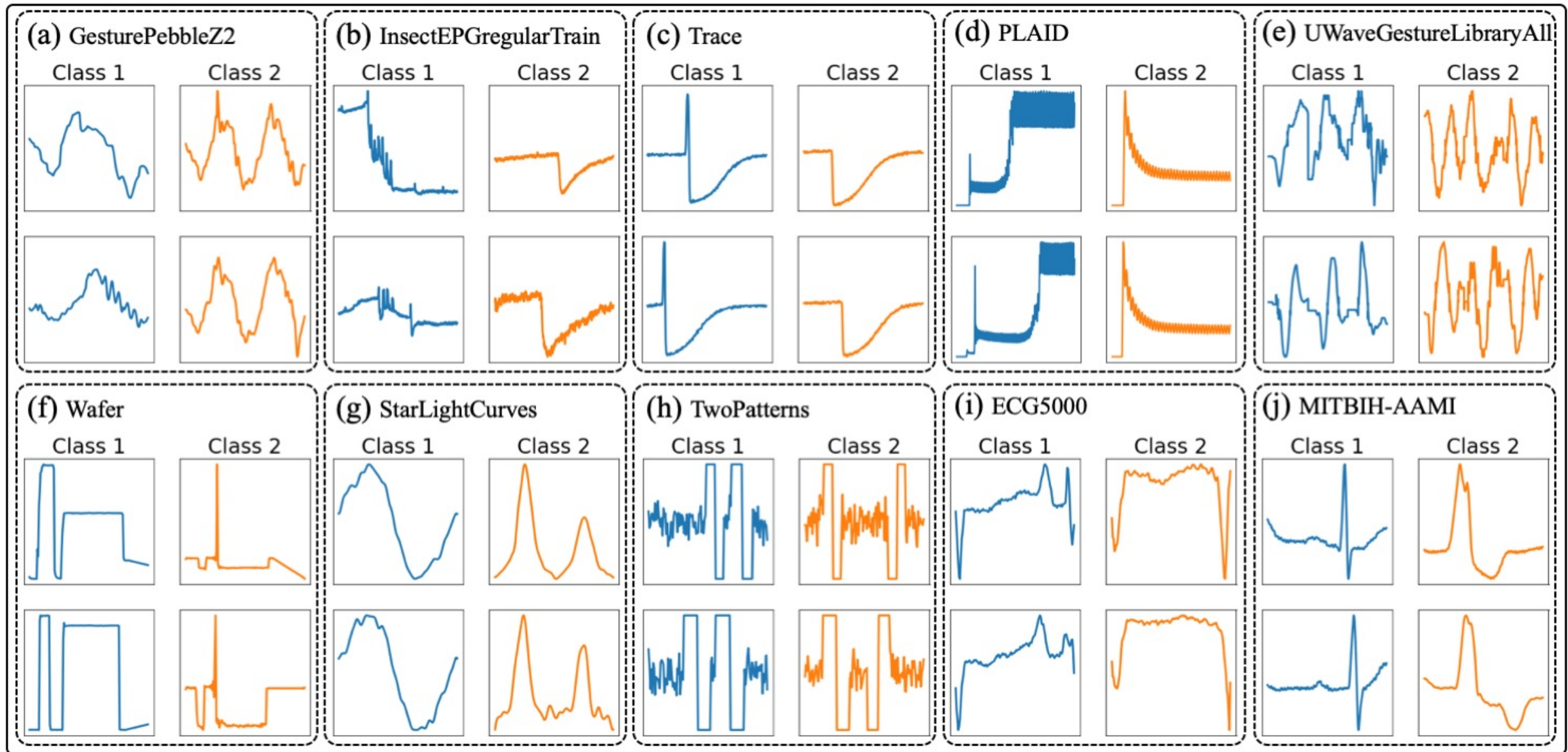


Subspace Enrichment:

$$\tilde{\hat{V}}_m^{(c)} = \text{span} \left(\{\hat{z}_1^{(c)\dagger}, \dots, \hat{z}_k^{(c)\dagger}\} \cup \mathbb{U}_T \cup \mathbb{U}_H \right)$$



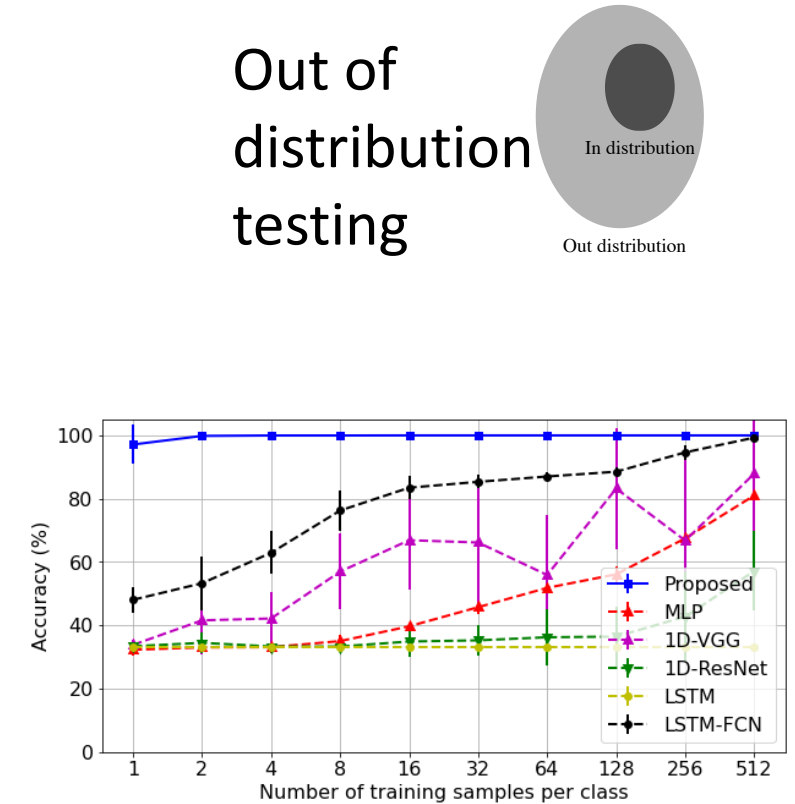
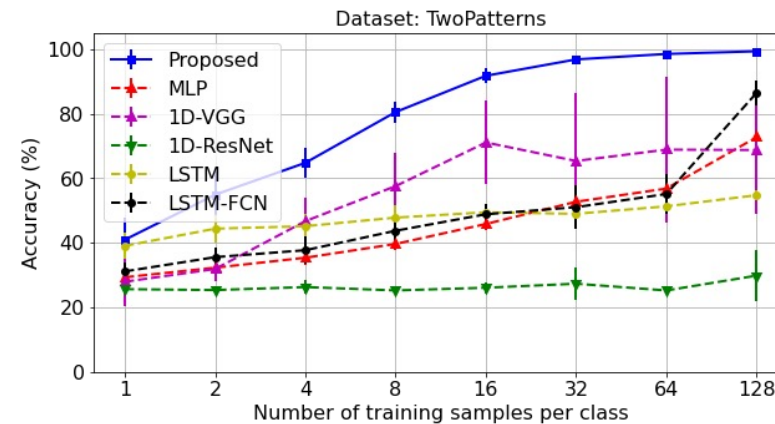
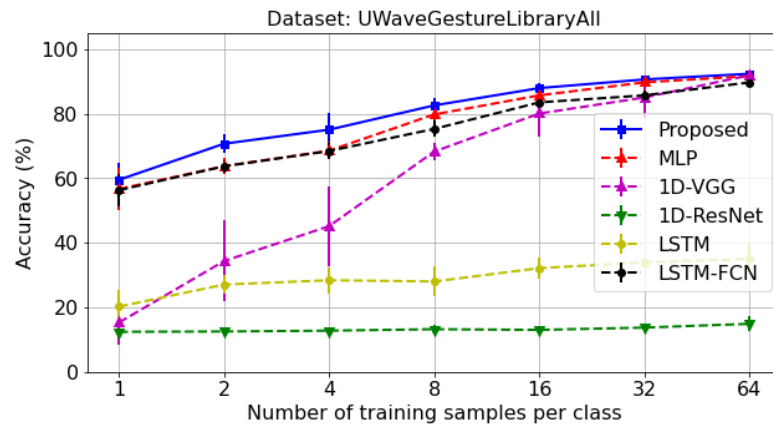
Solution is given by: $\arg \min_c d^2 \left(\hat{s}, \tilde{\hat{V}}_m^{(c)} \right)$



Results and comparisons with deep learning

[Rubaiyat et al, ArXiv 2022]

Dataset	MLP	1D-VGG	1D-ResNet	LSTM	LSTM-FCN	SCDT-NS	Proposed
GesturePebbleZ2	83.92	48.99	63.23	60.19	85.82	81.64	86.07
InsectEPGRegularTrain	80.92	82.07	50.58	57.05	59.95	73.43	90.82
Trace	64.0	35.8	25.9	28.2	58.1	85.0	88.0
PLAID	39.65	19.35	29.81	26.35	39.57	58.29	70.02
UWaveGestureLibraryAll	94.74	96.42	42.86	30.72	94.16	90.4	94.92
Wafer	68.69	94.03	53.66	51.36	86.70	92.75	95.53
StarLightCurves	75.85	70.0	56.53	60.54	74.38	77.4	84.2
TwoPatterns	88.12	95.15	87.42	80.62	98.47	95.15	99.92
ECG5000	98.9	98.92	98.92	98.36	98.76	93.4	97.4
MITBIH-AAMI	65.54	82.94	59.13	55.34	79.46	62.9	84.05
Win	0	2	1	0	0	0	8
AVG arithmetic ranking	3.5	3.5	5.6	6.3	3.6	3.8	1.6
AVG geometric ranking	3.42	2.8	5.07	6.27	3.46	3.49	1.28
MPCE	0.072	0.065	0.125	0.127	0.066	0.059	0.030

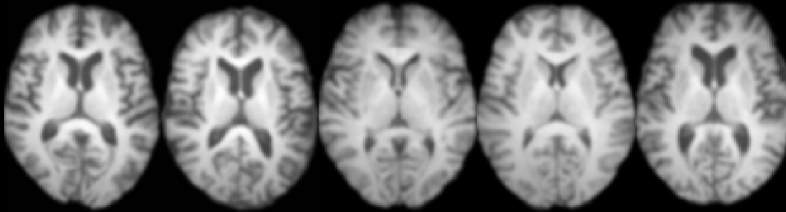


Transport-based Morphometry (TBM)

Biomedical image data science

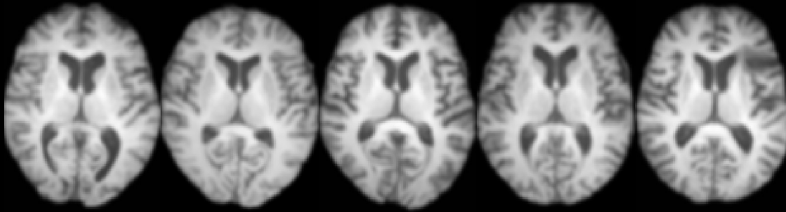
Are fitness and gray matter morphology related?

Class 1:
persons with low
fitness index



magnetic
resonance
imaging (MRI)

Class 2:
persons with high
fitness index

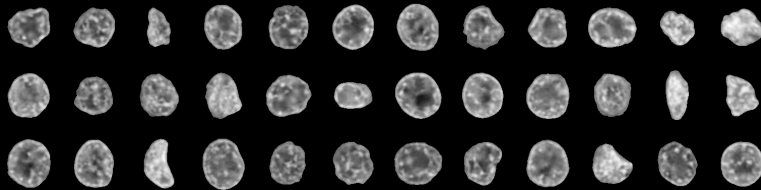


Hypothesis testing

Are there differences?

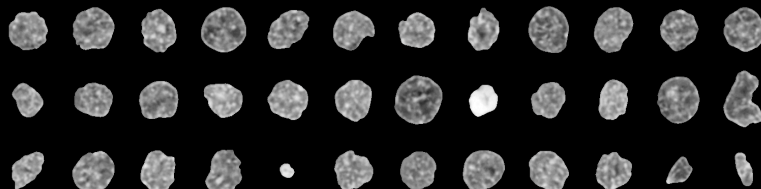
Is nuclear morphology related to cancer?

Class 1:
nuclei from
benign tissues



digital pathology
(microscopy)

Class 2:
nuclei from
malignant tissues

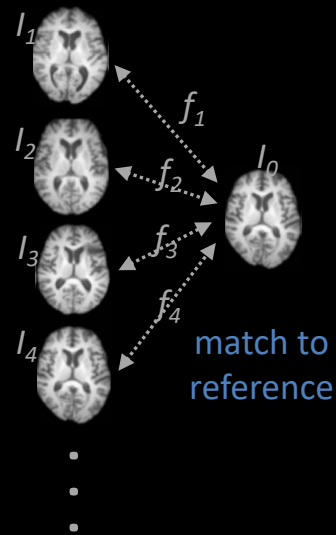


Understanding

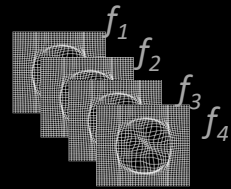
If so, can we model them?

Transport-based morphometry (TBM)

1) Transform



transport maps



2) regression

modeling variations

- PCA, least squares, ...

modeling differences

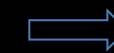
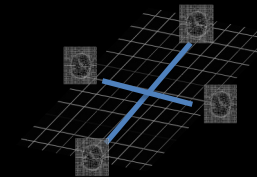
- LDA, SVM, ...

modeling relationships

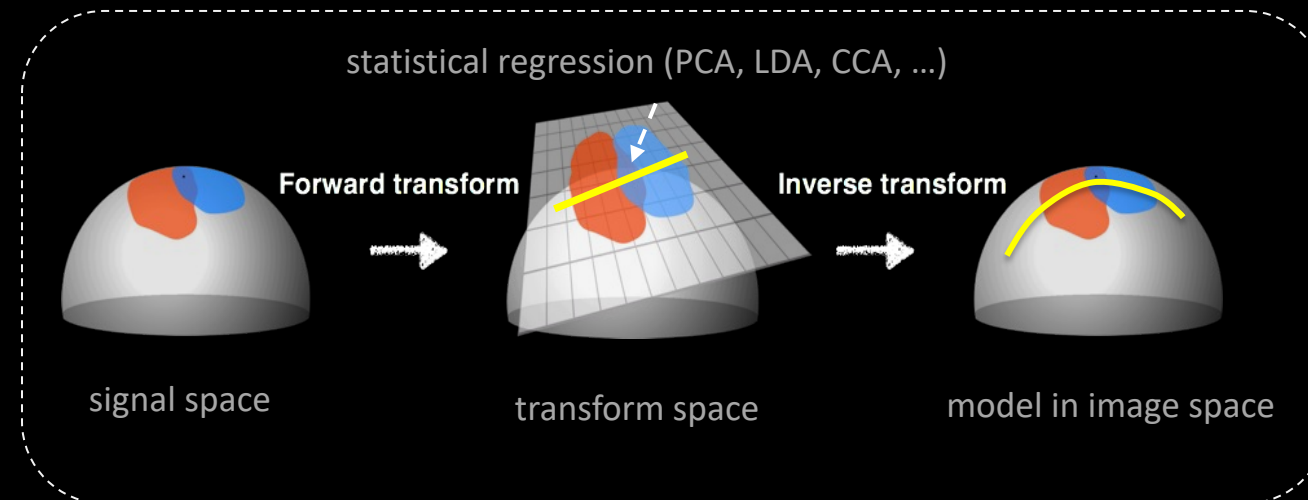
- CCA, ...

3) Inverse transform

PCA, LDA, CCA, ...



visualization

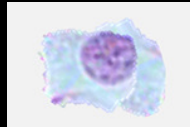
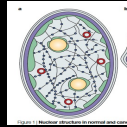


Example: nuclear structure in cancer

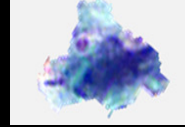
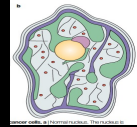
Aberrations in genetic
code and/or increase in
transcriptional activity



Unfolding/repackaging
of chromatin → change
in nuclear configuration

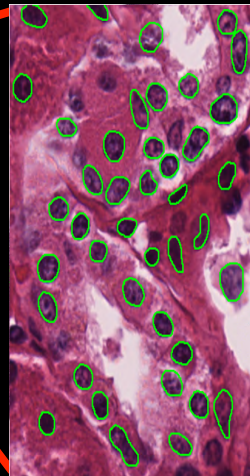
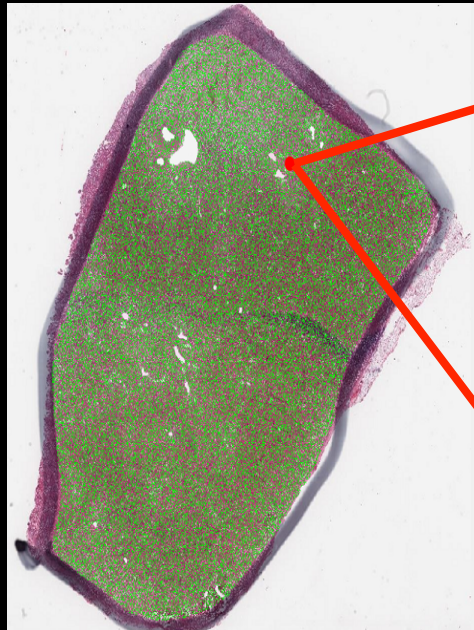


normal



cancer

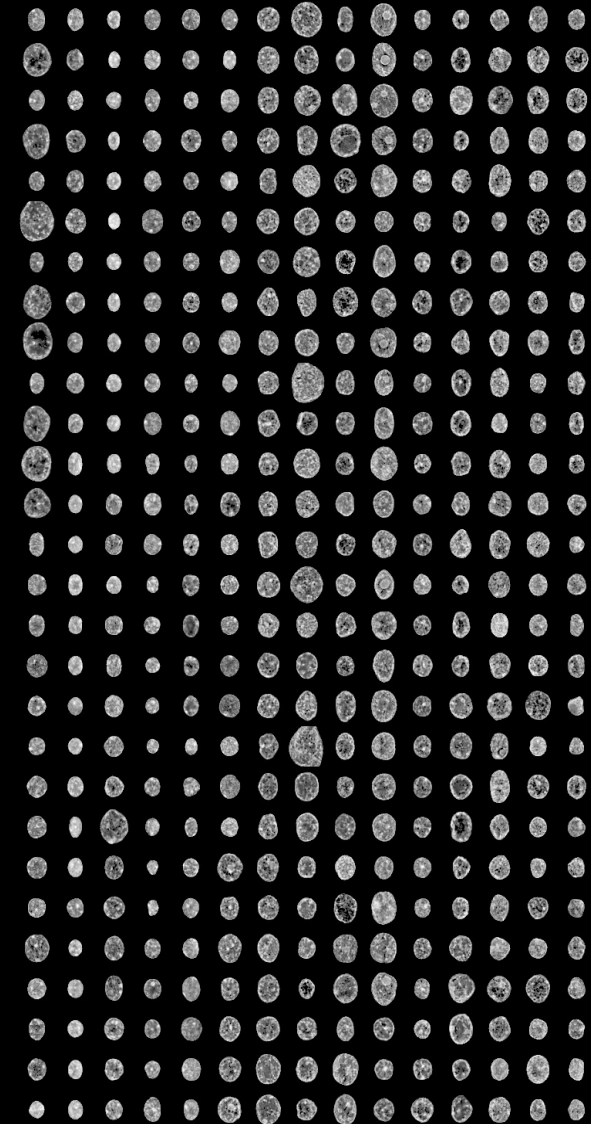
Pathology, whole slide imaging



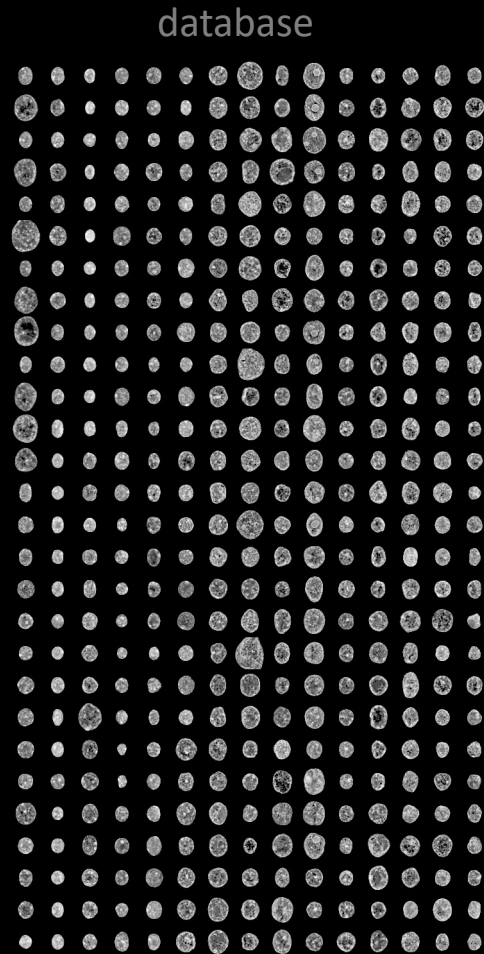
segmentation



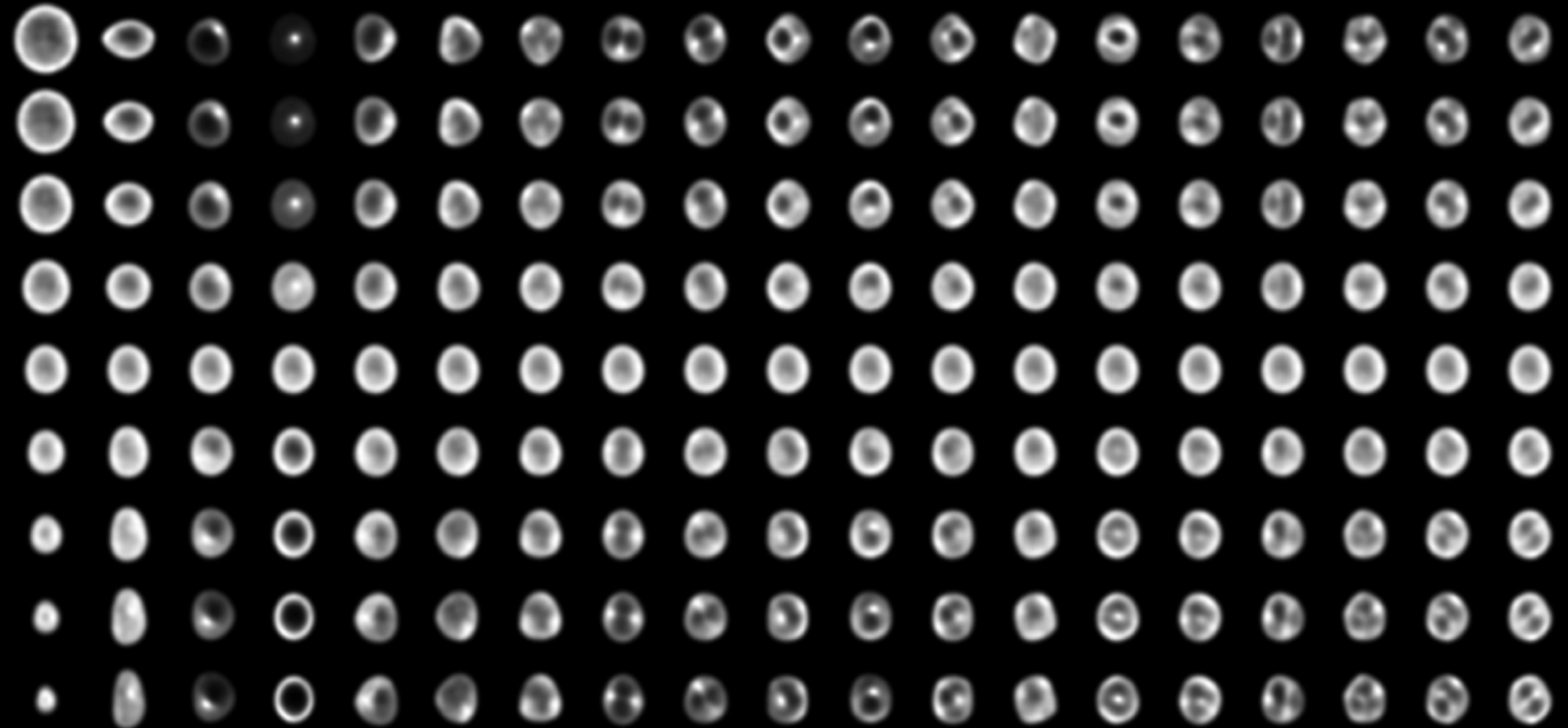
segmented nuclei



Exploratory analysis: PCA on transport maps



Modeling chromatin variation in liver cancer (shape + texture)



learned "features"

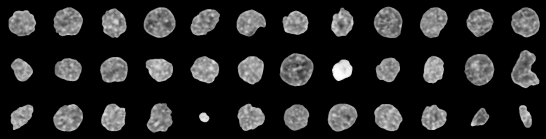
$$D_{f_\alpha^{-1}}(x)s_0(f_\alpha^{-1}(x))$$

$$f_\alpha(x) = \underbrace{f(x)}_{\text{mean}} + \alpha w(x) \leftarrow \text{PCA eigenvector}$$

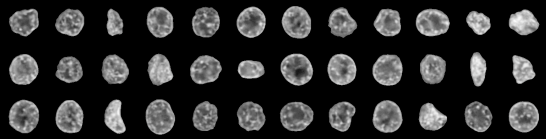
TBM: modeling discriminant information

[Basu et al, PNAS 2014]

Class 1: benign cells



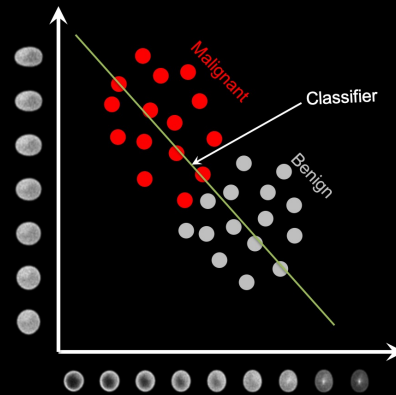
Class 2: malignant cells



forward



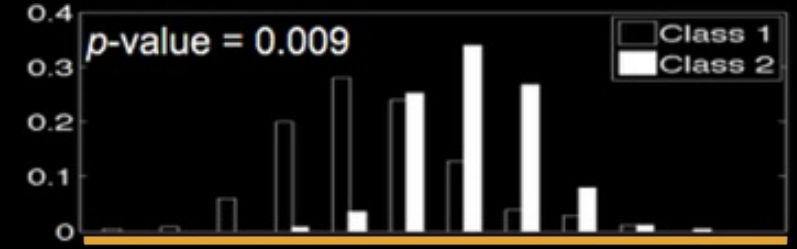
LDA in transport space



inverse



Fetal-type hepatoblastoma



Inverse of classification function

$$D_{f_{\alpha}^{-1}}(x) s_0(f_{\alpha}^{-1}(x))$$

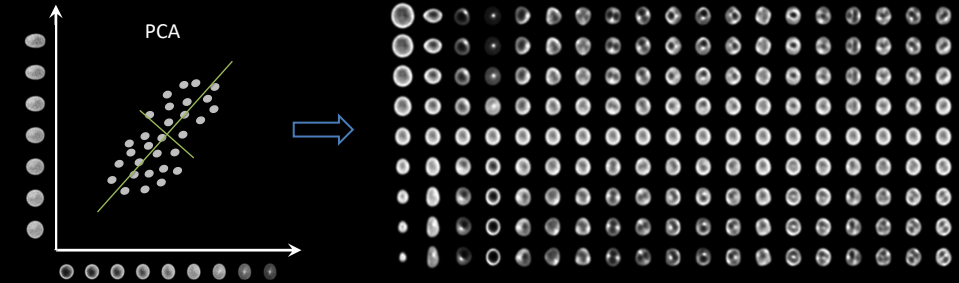
$$f_{\alpha}(x) = \underbrace{f(x)}_{\text{mean}} + \alpha w(x)$$

classifier

Summary: transport-based morphometry

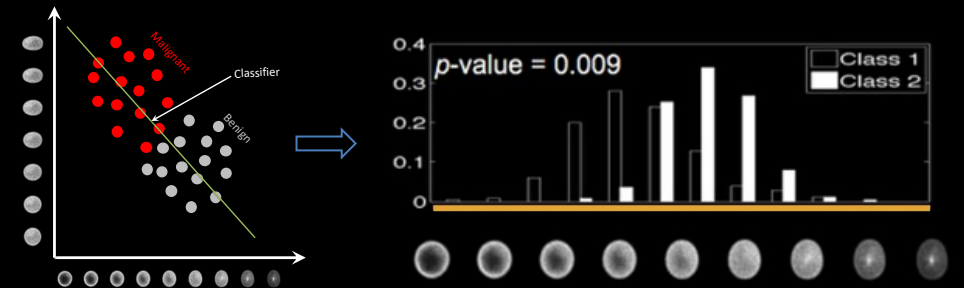
1) Exploratory analysis

- Transport PCA, subspace learning, ...
- Models texture & shape simultaneously
- Visualizes variations within dataset



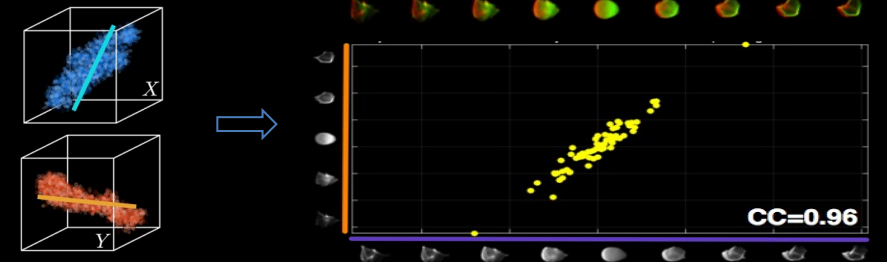
2) Discriminant models

- SVM, LDA, pLDA, ...
- Visualizes most discriminative information



3) Functional relationships

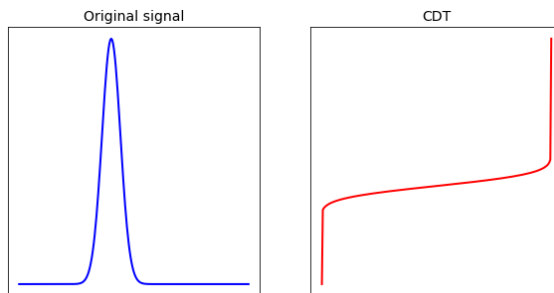
- CCA
- Study & visualize relationship between different measurements



Low level functions

```
x = np.arange(N)
mu = 100
sigma = 10
I1 = 1 / (sigma*np.sqrt(2*np.pi))*np.exp(-((x-mu)**2)/(2*sigma**2))
I1 = abs(I1) + epsilon
I1 = I1/I1.sum()
```

```
# compute the forward transform
I1_hat, f1_hat, xtile = cdt.forward(x0, I0, x, I1)
```



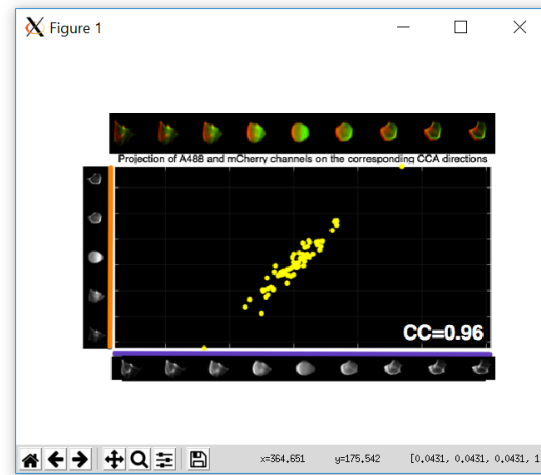
Command line tools

```
# load the neutrophils dataset
x, y = load_data('data/neutrophils')

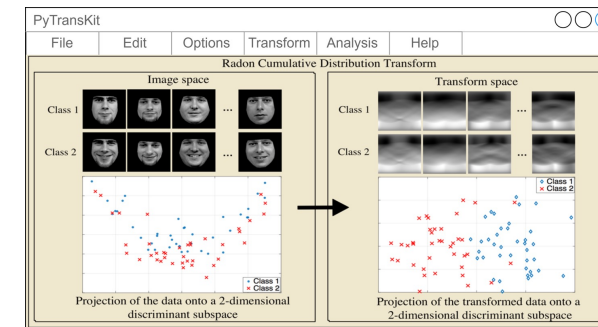
# R-CDT transform with default parameters
x_t = radoncdt.transform(x)

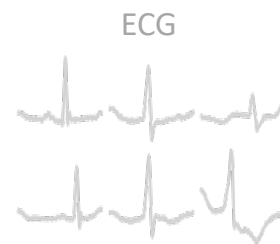
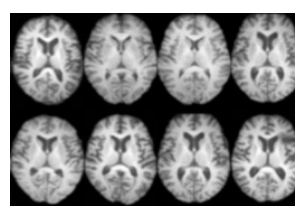
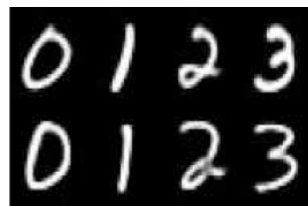
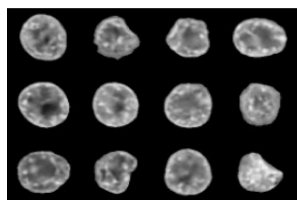
# CCA analysis, using 2 components
x_t_comps = cca.fit_transform(x_t, y, n_components=2)

# Show results
plt.plot(x_t_comps, y)
```



TBM toolbox





estimation, detection,
inverse problems, classification



signal space

$$\mathbb{S}^{(c)} = \bigcup_{m=1}^{M_c} \mathbb{S}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}};$$

$$\mathbb{S}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}} = \left\{ s_{j,m}^{(c)} \mid s_{j,m}^{(c)} = g'_j \varphi_m^{(c)} \circ g_j, g'_j > 0, g_j \in \mathcal{G}_m^{(c)} \right\}$$

transform space

$$\widehat{\mathbb{S}}^{(c)} = \bigcup_{m=1}^{M_c} \widehat{\mathbb{S}}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}},$$

$$\widehat{\mathbb{S}}_{\varphi_m^{(c)}, \mathcal{G}_m^{(c)}} = \left\{ \widehat{s}_{j,m}^{(c)} \mid \widehat{s}_{j,m}^{(c)} = g_j^{-1} \circ \widehat{\varphi}_m^{(c)}, g_j \in \mathcal{G}_m^{(c)} \right\}$$